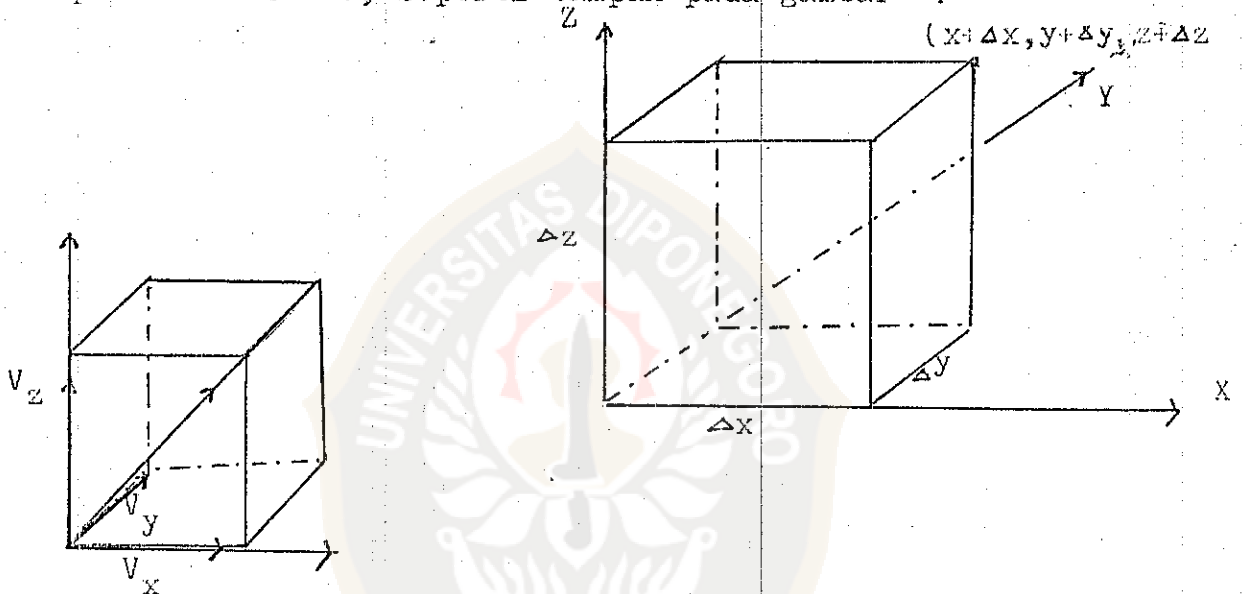


## BAB III

### PEMBENTUKAN MODEL

#### 3.1 KONTINUITAS ALIRAN FLUIDA

Suatu fluida yang mengalir pada sebuah benda yang berbentuk ku-  
bus dengan panjang sisi-sisinya  $\Delta x$ ,  $\Delta y$ ,  $\Delta z$  dan volume benda yg  
mempunyai kedudukan tetap dalam ruang. Fluida mengalir dengan -  
kecepatan sebesar  $\bar{V}$ , seperti tampak pada gambar :



Vektor kecepatan diuraikan sesuai arah koordinatnya yaitu :

$V_x$  = kecepatan pada arah x

$V_y$  = kecepatan pada arah y

$V_z$  = kecepatan pada arah z

Karena keadaan fluida bergerak maka fluida yang masuk pada  $x = x$   
akan keluar pada  $x = x + \Delta x$ . berlaku juga bila masuk pada  $y = y$   
maka akan keluar pada  $y = y + \Delta y$  dan juga untuk z, untuk menerap-  
kan persamaan (2) akan terbagi pada arah x, y dan z

Untuk arah x melalui bidang  $\Delta z \Delta y$  :

Luas bidang :  $\Delta z \cdot \Delta y$

Laju alir masa yang masuk :  $\Delta z \cdot \Delta y \cdot \rho V$  masuk pd  $x = x$

Laju alir masa yang keluar :  $\Delta z \cdot \Delta y \cdot \rho V$  keluar pd  $x = x + \Delta x$

Laju Akumulasi yg tertinggal :  $\Delta z \cdot \Delta y \cdot \Delta x \cdot \frac{\partial \rho}{\partial t}$

Sesuai dengan persamaan ( 1 ) yang menyatakan :

$$\text{Laju alir Akumulasi} = \text{Laju alir masuk} - \text{Laju alir keluar}$$

maka didapat bentuk :

$$\Delta z \Delta y \Delta x \frac{\partial \rho}{\partial t} = \Delta z \Delta y \cdot \rho^V_{\text{masuk pd } x = x} - \Delta z \Delta y \cdot \rho^V_{\text{keluar pd } x = x + \Delta x} \dots\dots\dots ( 7 )$$

Untuk arah y melalui bidang  $\Delta x \Delta z$

$$\text{Luas bidang} = \Delta x \cdot \Delta z$$

$$\text{Laju alir masa yang masuk} = \Delta x \cdot \Delta z \cdot \rho^V_{\text{masuk pd } y = y}$$

$$\text{Laju alir masa yg keluar} = \Delta x \cdot \Delta z \cdot \rho^V_{\text{keluar pd } y = y + \Delta y}$$

$$\text{Laju Akumulasi masa yg tinggal} = \Delta x \cdot \Delta z \cdot \Delta y \frac{\partial \rho}{\partial t}$$

Sesuai dengan persamaan ( 1 ) yang menyatakan :

$$\text{Laju alir Akumulasi} = \text{Laju alir masuk} - \text{Laju alir keluar}$$

maka di-dapat bentuk :

$$\Delta x \cdot \Delta z \cdot \Delta y \cdot \frac{\partial \rho}{\partial t} = \Delta x \Delta z \cdot \rho^V_{\text{masuk pd } y=y} - \Delta x \Delta z \cdot \rho^V_{\text{keluar pd } y=y+\Delta y} \dots\dots\dots ( 8 )$$

Untuk arah z melalui bidang  $\Delta x \Delta y$

$$\text{Luas bidang} = \Delta x \cdot \Delta y$$

$$\text{Laju alir masa yang masuk} = \Delta x \cdot \Delta y \cdot \rho^V_{\text{masuk pd } z=z}$$

$$\text{Laju alir masa keluar} = \Delta x \cdot \Delta y \cdot \rho^V_{\text{keluar pd } z=z+\Delta z}$$

$$\text{Laju akumulasi masa yang tinggal} = \Delta x \Delta y \Delta z \frac{\partial \rho}{\partial t}$$

Sesuai dengan persamaan ( 1 ) yang menyatakan :

$$\text{Laju Akumulasi masa} = \text{Laju alir masa yg masuk} - \text{Laju alir masa yg keluar.}$$

maka didapat bentuk :

$$\Delta x \Delta y \Delta z \frac{\partial \rho}{\partial t} = \Delta x \cdot \Delta y \cdot \rho^V_{\text{masuk pd } z=z} - \Delta x \cdot \Delta y \cdot \rho^V_{\text{keluar pd } z=z+\Delta z} \dots\dots\dots ( 9 )$$

Bila dari persamaan ( 7 ) , ( 8 ) dan ( 9 ) dijumlahkan bersama maka didapat :

" Persamaan Akumulasi Masa Seluruhnya "

$$\Delta z . \Delta y \frac{\partial \rho}{\partial t} = \Delta z . \Delta y \cdot \rho V_x|_x - \Delta z . \Delta y \cdot \rho V_x|_{x+\Delta x} .$$

+

$$\Delta x . \Delta z \frac{\partial \rho}{\partial t} = \Delta x \Delta z \cdot \rho V_y|_y - \Delta x \Delta z \cdot \rho V_y|_{y+\Delta y} .$$

+

$$\Delta x . \Delta y \frac{\partial \rho}{\partial t} = \Delta x \Delta y \cdot \rho V_z|_z - \Delta x \Delta y \cdot \rho V_z|_{z+\Delta z} .$$

dan disederhanakan :

$$\begin{aligned} \Delta x . \Delta y . \Delta z \frac{\partial \rho}{\partial t} &= \Delta y \Delta z \left[ \rho V_x|_x - \rho V_x|_{x+\Delta x} \right] \\ &+ \Delta x \Delta z \left[ \rho V_y|_y - \rho V_y|_{y+\Delta y} \right] \\ &+ \Delta y \Delta x \left[ \rho V_z|_z - \rho V_z|_{z+\Delta z} \right] \dots \dots \dots \end{aligned}$$

..... ( 10 )

Sekarang untuk persamaan (10) dibagi oleh  $\Delta x \Delta y \Delta z$  akan diperoleh bentuk :

$$\frac{\partial \rho}{\partial t} = \left\{ \frac{(\rho v_y)|_y - (\rho v_y)|_{y+\Delta y}}{\Delta y} \right\} + \left\{ \frac{(\rho v_z)|_z - (\rho v_z)|_{z+\Delta z}}{\Delta z} \right\} + \left\{ \frac{(\rho v_x)|_x - (\rho v_x)|_{x+\Delta x}}{\Delta x} \right\}$$

Tiap-tiap suku yang berselisih diambil harga limitnya untuk

$\Delta x$  mendekati 0

$\Delta y$  mendekati 0

$\Delta z$  mendekati 0

Sehingga :

$$\frac{\partial \rho}{\partial t} = \lim_{\Delta y \rightarrow 0} \left\{ \frac{(\rho v_y)|_y - (\rho v_y)|_{y+\Delta y}}{\Delta y} \right\} +$$

$$\lim_{\Delta z \rightarrow 0} \left\{ \frac{(\rho v_z)|_z - (\rho v_z)|_{z+\Delta z}}{\Delta z} \right\} +$$

$$\lim_{\Delta x \rightarrow 0} \left\{ \frac{(\rho v_x)|_x - (\rho v_x)|_{x+\Delta x}}{\Delta x} \right\}$$

atau :

$$\frac{\partial \rho}{\partial t} = - \frac{\partial(\rho v_x)}{\partial x} - \frac{\partial(\rho v_y)}{\partial y} - \frac{\partial(\rho v_z)}{\partial z}$$

atau :

$$\frac{\partial \rho}{\partial t} + \frac{\partial(\rho v_x)}{\partial x} + \frac{\partial(\rho v_y)}{\partial y} + \frac{\partial(\rho v_z)}{\partial z} = 0$$

Maka :

$$\frac{\partial \rho}{\partial t} + \frac{\partial (\rho v_x)}{\partial x} + \frac{\partial (\rho v_y)}{\partial y} + \frac{\partial (\rho v_z)}{\partial z} = 0$$

..... ( 11 )

dimana :

t = waktu

$\rho$  = density

$v_x$  ,  $v_y$  ,  $v_z$  = kecepatan ke arah x , y , z



### 3.2 KONTINUITAS DALAM LINGKARAN (SILINDER)

Untuk mendapatkan Model Matematik dalam bentuk Lingkaran ( Sy - linder ), diambil koordinat polar. Sedangkan hubungan antara koordinat polar dan koordinat kartesius sbb :

$$x = r \cos \phi$$

$$y = r \sin \phi$$

Sehingga Model Matematik dari persamaan (11 )

$$\frac{\partial \rho}{\partial t} + \frac{\partial(\rho v_x)}{\partial x} + \frac{\partial(\rho v_y)}{\partial y} + \frac{\partial(\rho v_z)}{\partial z} = 0$$

dapat dirubah dalam bentuk polar dengan menggunakan hubungan diatas. Sebelumnya kita bahas terlebih dahulu substitusinya.

$$dx = \cos \phi dr - r \sin \phi d\phi$$

$$dy = \sin \phi dr + r \cos \phi d\phi$$

Untuk mendapatkan harga dari dr dan dφ dicari dengan cara determinan Jacobi :

$$dr = \frac{\begin{vmatrix} dx & -r \sin \phi \\ dy & r \cos \phi \end{vmatrix}}{\begin{vmatrix} \cos \phi & -r \sin \phi \\ \sin \phi & r \cos \phi \end{vmatrix}}$$

$$= \frac{r (\cos \phi dx + \sin \phi dy)}{r.1}$$

Sedang untuk  $d\phi$  :

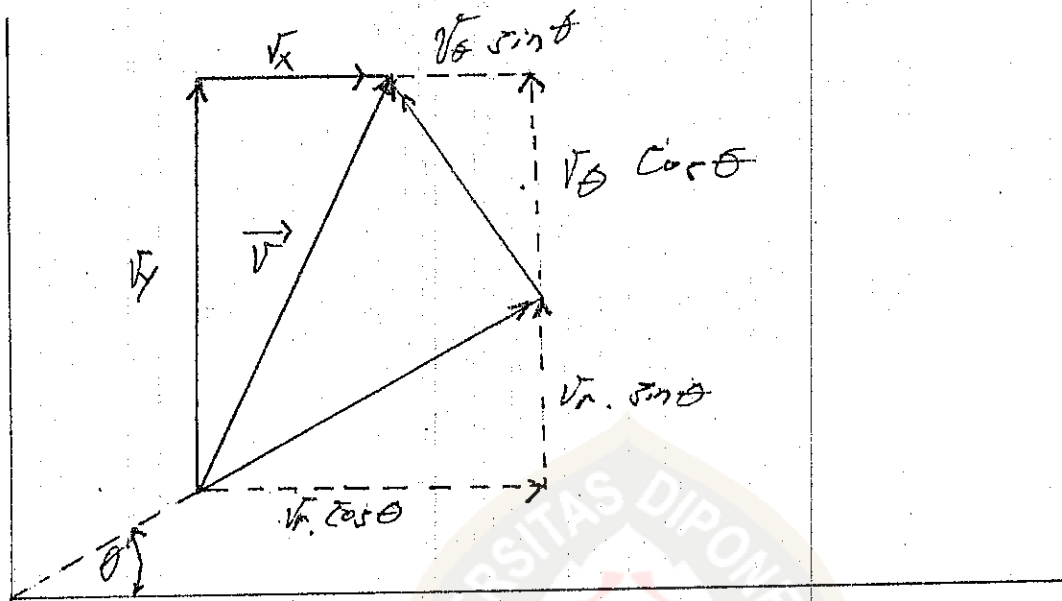
$$d\phi = \frac{\begin{vmatrix} \cos \phi & dx \\ \sin \phi & dy \end{vmatrix}}{\begin{vmatrix} \cos \phi & -r \sin \phi \\ \sin \phi & r \cos \phi \end{vmatrix}}$$
$$= \frac{-\sin \phi dx + \cos \phi dy}{r \cdot 1}$$
$$dr = \frac{\partial r}{\partial x} dx + \frac{\partial r}{\partial y} dy = \cos \phi dx + \sin \phi dy$$
$$d\phi = \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy = \frac{-\sin \phi}{r} dx + \frac{\cos \phi}{r} dy$$

Sehingga diperoleh :

$$\frac{\partial r}{\partial x} = \cos \phi \quad \text{dan} \quad \frac{\partial r}{\partial y} = \sin \phi$$

$$\frac{\partial \phi}{\partial x} = \frac{-\sin \phi}{r} \quad \text{dan} \quad \frac{\partial \phi}{\partial y} = \frac{\cos \phi}{r}$$

Untuk kecepatan vektor  $V$  diuraikan pada arah  $x$  dan  $y$  seperti tampak pada gambar :



$$V_x = V_r \cos \theta - V_\theta \sin \theta$$

$$V_y = V_\theta \cos \theta + V_r \sin \theta$$

Perhatikan untuk :

$$\frac{\partial(\rho V_x)}{\partial x} = \frac{\partial(\rho V_x)}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial(\rho V_x)}{\partial \theta} \frac{\partial \theta}{\partial x} + \frac{\partial(\rho V_x)}{\partial z} \frac{\partial z}{\partial x}$$

$$= \frac{\partial}{\partial r} [V_r \cos \theta - V_\theta \sin \theta] \cdot \cos \theta +$$

$$\frac{\partial}{\partial \theta} [V_r \sin \theta + V_\theta \cos \theta] \cdot \frac{-\sin \theta}{r}$$

$$\frac{\partial(\rho V_y)}{\partial y} = \frac{\partial(\rho V_y)}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial(\rho V_y)}{\partial \theta} \frac{\partial \theta}{\partial y} + \frac{\partial(\rho V_y)}{\partial z} \frac{\partial z}{\partial y}$$

$$= \frac{\partial}{\partial r} [\rho V_r \sin \theta + \rho V_\theta \cos \theta] \cdot \cos \theta +$$

$$\frac{\partial}{\partial \theta} [\rho V_r \sin \theta + \rho V_\theta \cos \theta] \cdot \frac{\cos \theta}{r}$$



Maka :

$$\begin{aligned} \frac{\partial(\rho v_x)}{\partial x} + \frac{\partial(\rho v_y)}{\partial y} &= \frac{\partial}{\partial r} [\rho v_r \cos \phi - \rho v_\phi \sin \phi] \cdot \cos \phi \\ &+ \frac{\partial}{\partial \phi} [\rho v_r \sin \phi + \rho v_\phi \cos \phi] \cdot -\frac{\sin \phi}{r} + \frac{\partial}{\partial r} [\rho v_r \sin \phi \\ &+ \rho v_\phi \cos \phi] \cdot \sin \phi + \frac{\partial}{\partial \phi} [\rho v_r \sin \phi + \rho v_\phi \cos \phi] \cdot \\ \frac{\cos \phi}{r} &= \frac{1}{r} \frac{\partial}{\partial r} (r \rho v_r) + \frac{1}{r} \frac{\partial}{\partial \phi} (\rho v_\phi) \end{aligned}$$

Disubstitusikan pada persamaan (11) didapat :

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r} (r \rho v_r) + \frac{1}{r} \frac{\partial}{\partial \phi} (\rho v_\phi) = 0 \dots\dots (12)$$

dimana :

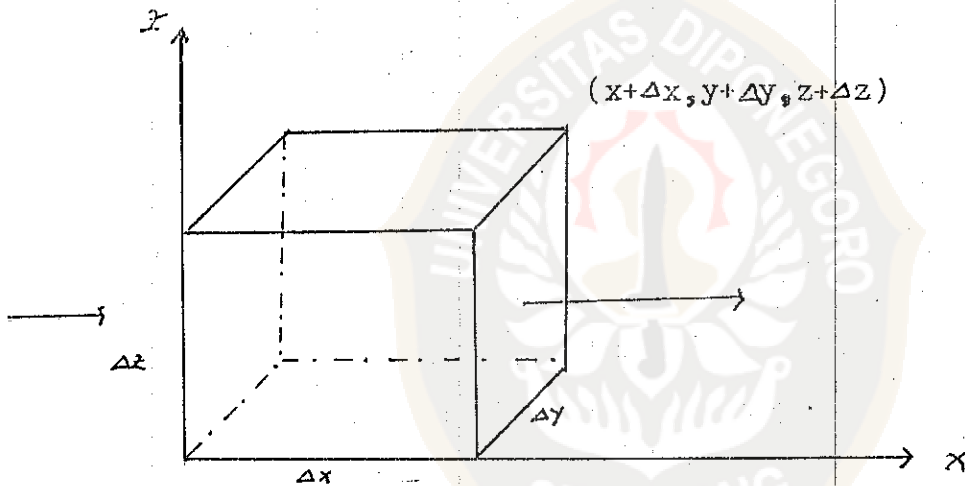
- $\rho$  = density masa
- $v_r$  = kecepatan ke arah r
- $v_\phi$  = kecepatan ke arah  $\phi$
- r = jari-jari
- t = waktu

### 3.3 GERAK DARI ALIRAN FLUIDA

Gerak dari aliran fluida merupakan kelanjutan dari Kontinuitas fluida. Untuk mendapatkan Model Persamaan Differensial dari Gerak Aliran diambil asumsi asumsi sbb :

- Arah perpindahan momentum dari fluida
- Perpindahan gaya
- Laju alir momentum

Dengan mengambil elemen kecil  $\Delta x, \Delta y, \Delta z$  sebagai sisi dari volume yang dilewati aliran fluida, seperti tampak pd gambar :



Karena keadaan fluida bergerak, maka fluida yang masuk akan segera keluar dari volume.

Bila fluida masuk pd  $x=x$ , maka akan keluar pd  $x=x+\Delta x$

Bila fluida masuk pd  $y=y$  maka akan keluar pd  $y=y+\Delta y$

Bila fluida masuk pd  $z=z$  maka akan keluar pd  $z=z+\Delta z$

Pada aliran ada perpindahan Momentum dari aliran dimana perpindahan momentum terpisah menjadi dua ( 2 ) yaitu ;

- Perpindahan Momentum
- Perpindahan Molekuler

Peristiwa perpindahan ini juga mengalami perpindahan arah sesuai dengan koordinatnya.

A. Pada arah x melalui bidang  $\Delta z \Delta y$  berpindah secara Konveksi

$$\text{Luas bidang} = \Delta z \cdot \Delta y$$

$$\text{Laju alir Momentum yg masuk} = \Delta z \Delta y \rho V_x \cdot V_{\text{masuk pd } x=x}$$

$$\text{Laju alir Moementum yg keluar} = \Delta z \Delta y \rho V_x \cdot V_{\text{keluar pd } x=x+\Delta x}$$

$$\text{Laju Akumulasi Momentum} = \Delta z \Delta y \cdot \Delta x \cdot \frac{\partial V_x}{\partial t}$$

Derigan menggunakan persamaan ( 3 ) maka

$$\text{Laju Akumulasi Momentum} = \text{Laju alir Momentum masuk} - \text{Laju alir Momentum keluar}$$

atau :

$$\Delta z \Delta y \Delta x \frac{\partial V_x}{\partial t} = \Delta z \Delta y \rho V_x V_{\text{masuk pd } x=x} - \Delta z \Delta y \rho V_x V_{\text{klr } x+\Delta x}$$

Sedang perpindahan Molekuler pd arah x :

$$\text{Luas bidang} : \Delta z \cdot \Delta y$$

$$\text{Laju Akumulasi Momentum} = \text{Laju alir momentum masuk} - \text{Laju alir Momentum keluar.}$$

$$\text{Laju Akumulasi} = \Delta z \Delta y \tau_x \text{ masuk pd } x=x - \Delta z \Delta y \tau_x \text{ keluar pd } x=x + \Delta x$$

Untuk perpindahan tekanan dan grafitasi :

$$\begin{aligned} \text{Akumulasi tekanan} &= \Delta z \Delta y \cdot p |_{\text{masuk pd } x=x} - \Delta z \Delta y \cdot p |_{\text{keluar } x=x+\Delta x} \\ &+ g_x \Delta x \Delta y \Delta z \end{aligned}$$

Untuk Laju Akumulasi Momentum arah x menimbulkan perpindahan Momentum ke arah y.

$$\text{Luas bidang} = \Delta x \Delta z$$

$$\text{Konveksi} : \Delta x \Delta z \rho V_x V_{\text{masuk pd } y=y} - \Delta x \Delta z \rho V_x V_{\text{keluar pd } y=y+\Delta y}$$

$$\text{Molekuler} : \Delta x \Delta z \tau_x \text{ masuk pd } y=y - \Delta x \Delta z \tau_x \text{ keluar pd } y=y+\Delta y$$

Untuk Laju Akumulasi Momentum arah x menimbulkan perpindahan Momentum ke arah z.

$$\text{Luas bidang} = \Delta x \Delta y$$

Laju Akumulasi berpindah secara :

Konveksi :  $\Delta x \Delta y \rho V_x V$  masuk pd  $z=z$  -  $\Delta x \Delta y \rho V_x V$  keluar  $z=z+\Delta z$

Molekuler :  $\Delta x \Delta y \tau_x$  masuk pd  $z=z$  -  $\Delta x \Delta y \tau_x$  keluar pd  $z=z+\Delta z$

Jadi didapat Laju Akumulasi Momentum keseluruhan pada arah x :

$$\begin{aligned} \Delta x \Delta y \Delta z \frac{\partial V_x}{\partial t} &= \Delta y \Delta z (\rho V_x V_x|_x - \rho V_x V_x|_{x+\Delta x}) \\ &+ \Delta x \Delta z (\rho V_x V_y|_y - \rho V_x V_y|_{y+\Delta y}) \\ &+ \Delta x \Delta y (\rho V_x V_z|_z - \rho V_x V_z|_{z+\Delta z}) \\ &+ \Delta y \Delta z (\tau_{xx}|_x - \tau_{xx}|_{x+\Delta x}) \\ &+ \Delta x \Delta z (\tau_{xy}|_y - \tau_{xy}|_{y+\Delta y}) \\ &+ \Delta x \Delta y (\tau_{xz}|_z - \tau_{xz}|_{z+\Delta z}) \\ &+ \Delta y \Delta z (p|_x - p|_{x+\Delta x}) \end{aligned}$$

Setiap suku persamaan ini dibagi oleh  $\Delta x \Delta y \Delta z$  maka :

$$\frac{\partial \rho V_x}{\partial t} = \frac{(\rho V_x V_x|_x - \rho V_x V_x|_{x+\Delta x})}{\Delta x} + \frac{(\rho V_x V_y|_y - \rho V_x V_y|_{y+\Delta y})}{\Delta y}$$

$$+ \frac{(\rho V_x V_z|_z - \rho V_x V_z|_{z+\Delta z})}{\Delta z} + \frac{(\tau_{xx}|_x - \tau_{xx}|_{x+\Delta x})}{\Delta x}$$

$$+ \frac{(\tau_{xy}|_y - \tau_{xy}|_{y+\Delta y})}{\Delta y} + \frac{(\tau_{xz}|_z - \tau_{xz}|_{z+\Delta z})}{\Delta z}$$

$$+ \frac{(p|_x - p|_{x+\Delta x})}{\Delta x} + \rho g_x$$

Karena harga-harga  $\Delta x \Delta y \Delta z$  kecil sekali maka diambil harga limitnya untuk  $\Delta x \rightarrow 0$ ,  $\Delta y \rightarrow 0$  dan  $\Delta z \rightarrow 0$  sehingga :

$$= \lim_{\Delta x \rightarrow 0} \frac{(\rho V_x V_x|_x - \rho V_x V_x|_{x+\Delta x})}{\Delta x}$$

$$+ \lim_{\Delta y \rightarrow 0} \frac{(\rho V_x V_y|_y - \rho V_x V_y|_{y+\Delta y})}{\Delta y}$$

$$+ \lim_{\Delta z \rightarrow 0} \frac{(\rho V_x V_z|_z - \rho V_x V_z|_{z+\Delta z})}{\Delta z}$$

$$+ \lim_{\Delta x \rightarrow 0} \frac{(\tau_{xx}|_x - \tau_{xx}|_{x+\Delta x})}{\Delta x}$$

$$+ \lim_{\Delta y \rightarrow 0} \frac{(\tau_{xy}|_y - \tau_{xy}|_{y+\Delta y})}{\Delta y}$$

$$+ \lim_{\Delta z \rightarrow 0} \frac{(\tau_{xz}|_z - \tau_{xz}|_{z+\Delta z})}{\Delta z}$$

$$+ \lim_{\Delta x \rightarrow 0} \frac{(\rho|_x - \rho|_{x+\Delta x})}{\Delta x} + \rho g_x$$

maka ;

$$\frac{\partial \rho v_x}{\partial t} = \frac{\partial \rho v_x v_x}{\partial x} - \frac{\partial \rho v_x v_y}{\partial y} - \frac{\partial \rho v_x v_z}{\partial z} - \frac{\partial \tau_{xx}}{\partial x} - \frac{\partial \tau_{xy}}{\partial y} - \frac{\partial \tau_{xy}}{\partial y} - \frac{\partial \tau_{xz}}{\partial z} - \frac{\partial p}{\partial x} + \rho g_x$$

atau ;

$$\frac{\partial \rho v_x}{\partial t} + \frac{\partial \rho v_x v_x}{\partial x} + \frac{\partial \rho v_x v_y}{\partial y} + \frac{\partial \rho v_x v_z}{\partial z} = - \left( \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z} \right) - \frac{\partial p}{\partial x} + \rho g_x$$

untuk ruas kiri dideffrensialkan

$$\rho \left( \frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) + v_x \left( \frac{\partial \rho}{\partial t} + \frac{\partial \rho v_y}{\partial y} + \frac{\partial \rho v_x}{\partial x} + \frac{\partial \rho v_z}{\partial z} \right) = - \left( \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z} \right) + \frac{\partial p}{\partial x} + \rho g_x$$

Menurut persamaan Kontinuitas :

$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho v_x}{\partial x} + \frac{\partial \rho v_y}{\partial y} + \frac{\partial \rho v_z}{\partial z} = 0$$

Sehingga persamaan berubah menjadi :

$$\rho \left( \frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) = - \left( \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z} \right) + \left( - \frac{\partial p}{\partial x} \right) + \rho g_x$$

dimana :

index pertama menyatakan arah perpindahan

index kedua menyatakan arah vektor

$V$  = kecepatan fluida

$p$  = gaya tekan

$g$  = gaya gravitasi

$\tau$  = tegangan geser

B. Pada arah : y melalui bidang  $\Delta x \Delta z$

$$\text{Luas bidang} = \Delta x \cdot \Delta z$$

Berpindah secara Konveksi :

Laju alir Momentum yg masuk bidang =  $\Delta x \Delta z \rho V_y \cdot V$  masuk pd  $y=y$

Laju alir Momentum yg keluar bidang =  $\Delta x \Delta z \rho V_y \cdot V$  keluar pd  $y=y+\Delta y$

$$\text{Laju Akumulasi Momentum} = \Delta z \Delta x \Delta y \frac{\partial V_y}{\partial t}$$

Dengan menggunakan persamaan ( 5 ), maka :

$$\Delta z \Delta x \Delta y \frac{\partial V_y}{\partial t} = \Delta x \Delta z \rho V_y V \text{ masuk pd } y=y - \Delta x \Delta z \rho V_y V \text{ keluar } y=y+\Delta y$$

Berpindah secara molekuler :

Laju Akumulasi Momentum =  $\Delta x \Delta z \mathcal{J}_y$  masuk pd  $y=y - \Delta x \Delta z \mathcal{J}_y$  keluar  $y=y+\Delta y$

Pemindahan Momentum oleh tekanan :  $(p|_y - p|_{y+\Delta y})$

Pemindahan grafitasi :  $g_y \Delta x \Delta y \Delta z$

Laju Akumulasi Momentum arah y menimbulkan perpindahan Momentum ke arah z

$$\text{Luas bidang} = \Delta x \Delta y$$

Perpindahan secara :

Konveksi :  $\Delta x \Delta y \rho V_y V$  msk pd  $z=z - \Delta x \Delta y \rho V_y V$  klr pd  $z=z+\Delta z$

Molekuler :  $\Delta x \Delta y \mathcal{J}_y$  msk pd  $z=z - \Delta x \Delta y \mathcal{J}_y$  klr pd  $z=z+\Delta z$

Laju Akumulasi Momentum ke arah y menimbulkan perpindahan

Momentum ke arah x

$$\text{Luas bidang} = \Delta y \Delta z$$

Perpindahan secara :

Konveksi :  $\Delta y \Delta z \rho V_x V$  msk pd  $x=x - \Delta y \Delta z \rho V_x V$  klr pd  $x=x+\Delta x$

Molekuler :  $\Delta y \Delta z \mathcal{J}_x$  msk pd  $x=x - \Delta y \Delta z \mathcal{J}_x$  klr pd  $x=x+\Delta x$



Jadi jumlah Laju Akumulasi Momentum ke arah  $y$  :

$$\begin{aligned} \Delta x \Delta y \Delta z \frac{\partial v_y}{\partial t} &= \Delta x \Delta z \rho v_y v_y - \Delta x \Delta z \rho v_y v_y|_{y+\Delta y} \\ &+ \Delta y \Delta z \rho v_y v_x - \Delta y \Delta z \rho v_y v_x|_{x+\Delta x} \\ &+ \Delta x \Delta y \rho v_y v_z - \Delta x \Delta y \rho v_y v_z|_{z+\Delta z} \\ &+ \Delta x \Delta z \tau_{yy}|_y - \Delta x \Delta z \tau_{yy}|_{y+\Delta y} \\ &+ \Delta y \Delta z \tau_{yx}|_x - \Delta y \Delta z \tau_{yx}|_{x+\Delta x} \\ &+ \Delta x \Delta y \tau_{yz}|_z - \Delta x \Delta y \tau_{yz}|_{z+\Delta z} \\ &+ \Delta x \Delta z (p|_y - p|_{y+\Delta y}) + \Delta x \Delta y \Delta z \epsilon_y \end{aligned}$$

Setiap suku dari persamaan ini dibagi dengan  $\Delta x \Delta y \Delta z$ , maka :

$$\begin{aligned} \frac{\partial \rho v_y}{\partial t} &= \frac{(\rho v_x v_y|_x - \rho v_x v_y|_{x+\Delta x})}{\Delta x} + \frac{(\rho v_y v_y|_y - \rho v_y v_y|_{y+\Delta y})}{\Delta y} \\ &+ \frac{(\rho v_z v_y|_z - \rho v_z v_y|_{z+\Delta z})}{\Delta z} + \frac{(\tau_{xy}|_x - \tau_{xy}|_{x+\Delta x})}{\Delta x} \\ &+ \frac{(\tau_{yy}|_y - \tau_{yy}|_{y+\Delta y})}{\Delta y} + \frac{(\tau_{zy}|_z - \tau_{zy}|_{z+\Delta z})}{\Delta z} \\ &+ \frac{(p|_y - p|_{y+\Delta y})}{\Delta y} + \rho \epsilon_y \end{aligned}$$

Karena harga-harga dari  $\Delta x, \Delta y, \Delta z$  kecil sekali maka diambil harga limitnya untuk  $\Delta x, \Delta y, \Delta z$  mendekati nol, sehingga :

$$\begin{aligned} &= \lim_{\Delta x \rightarrow 0} \frac{(\rho v_x v_y|_x - \rho v_x v_y|_{x+\Delta x})}{\Delta x} + \lim_{\Delta y \rightarrow 0} \frac{(\rho v_y v_y|_y - \rho v_y v_y|_{y+\Delta y})}{\Delta y} \\ &+ \lim_{\Delta z \rightarrow 0} \frac{(\rho v_z v_y|_z - \rho v_z v_y|_{z+\Delta z})}{\Delta z} \end{aligned}$$

$$\begin{aligned}
& + \lim_{\Delta x \rightarrow 0} \left( \frac{\tau_{xy}|_x - \tau_{xy}|_{x+\Delta x}}{\Delta x} \right) \\
& + \lim_{\Delta y \rightarrow 0} \left( \frac{\tau_{yy}|_y - \tau_{yy}|_{y+\Delta y}}{\Delta y} \right) \\
& + \lim_{\Delta z \rightarrow 0} \left( \frac{\tau_{zy}|_z - \tau_{zy}|_{z+\Delta z}}{\Delta z} \right) \\
& + \lim_{\Delta y \rightarrow 0} \left( \frac{p|_y - p|_{y+\Delta y}}{\Delta y} \right) + \rho g_y
\end{aligned}$$

maka :

$$\begin{aligned}
\frac{\partial \rho v_y}{\partial t} = & - \left( \frac{\partial \rho v_x v_y}{\partial x} + \frac{\partial \rho v_y v_y}{\partial y} + \frac{\partial \rho v_z v_y}{\partial z} \right) - \frac{\partial \tau_{xy}}{\partial x} - \frac{\partial \tau_{yy}}{\partial y} \\
& - \frac{\partial \tau_{zy}}{\partial z} - \frac{\partial p}{\partial y} + \rho g_y
\end{aligned}$$

atau :

$$\begin{aligned}
\frac{\partial \rho v_y}{\partial t} + \frac{\partial \rho v_x v_y}{\partial x} + \frac{\partial \rho v_y v_y}{\partial y} + \frac{\partial \rho v_z v_y}{\partial z} = & - \frac{\partial \tau_{xy}}{\partial x} - \frac{\partial \tau_{yy}}{\partial y} \\
& - \frac{\partial \tau_{zy}}{\partial z} - \frac{\partial p}{\partial y} + \rho g_y
\end{aligned}$$

atau :

$$\frac{\partial \rho v_y}{\partial t} + \frac{\partial \rho v_x v_y}{\partial x} + \frac{\partial \rho v_y v_y}{\partial y} + \frac{\partial \rho v_z v_y}{\partial z} = - \frac{\partial \tau_{xy}}{\partial x} - \frac{\partial \tau_{yy}}{\partial y} - \frac{\partial \tau_{zy}}{\partial z}$$

$$- \frac{\partial p}{\partial y} + \rho g_y$$

Untuk ruas kanan dideffrensialkan sehingga didapat :

$$\rho \left( \frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) + v_y \left( \frac{\partial \rho}{\partial t} + \frac{\partial \rho v_x}{\partial x} + \frac{\partial \rho v_y}{\partial y} + \frac{\partial \rho v_z}{\partial z} \right) = - \left\{ \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} \right\} - \frac{\partial p}{\partial y} + \rho g_y$$

Sesuai dengan persamaan Kontinuitas :

$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho v_x}{\partial x} + \frac{\partial \rho v_y}{\partial y} + \frac{\partial \rho v_z}{\partial z} = 0$$

Sehingga didapat persamaan :

$$\rho \left( \frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) = - \left( \frac{\partial \tau_{yx}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{yz}}{\partial z} \right) - \frac{\partial p}{\partial y} + \rho g_y$$

dimana :

index pertama menyatakan arah perpindahan

index kedua menyatakan arah vektor

V = kecepatan fluida

p = gaya tekan

g = gaya gravitasi

$\tau$  = tegangan geser

Pada arah z :

$$\Delta y \Delta z (\rho v_x v_z|_x - \rho v_x v_z|_{x+\Delta x}) + \Delta x \Delta z (\rho v_y v_z|_y - \rho v_y v_z|_{y+\Delta y}) + \Delta x \Delta y (\rho v_z v_z|_z - \rho v_z v_z|_{z+\Delta z})$$

Demikian juga untuk perpindahan gaya gesernya :

$$\Delta y \Delta z (\tau_{xz}|_x - \tau_{xz}|_{x+\Delta x}) + \Delta x \Delta z (\tau_{yz}|_y - \tau_{yz}|_{y+\Delta y}) + \Delta x \Delta y (\tau_{zz}|_z - \tau_{zz}|_{z+\Delta z})$$

Untuk gaya tekan dan gaya gravitasinya :

$$\Delta x \Delta y (p|_z - p|_{z+\Delta z}) + \rho g_z$$

$\rho V =$  laju akumulasi yang tergantung pada perubahan waktu

jadi ;  $\lim_{t \rightarrow 0} \frac{(t + \Delta t) - t}{\Delta t} = \frac{\partial \rho V}{\partial t}$

Dengan menggunakan Hukum Kekekalan Masa :

$$\Delta x \Delta y \Delta z \frac{\partial \rho V}{\partial t} = \Delta y \Delta z (\rho v_x v_z|_x - \rho v_x v_z|_{x+\Delta x}) + \Delta x \Delta z (\rho v_y v_z|_y - \rho v_y v_z|_{y+\Delta y}) + \Delta x \Delta y (\rho v_z v_z|_z - \rho v_z v_z|_{z+\Delta z})$$

$$\begin{aligned}
& + \Delta y \Delta z ( \tau_{xz}|_x - \tau_{xz}|_{x+\Delta x} ) \\
& + \Delta x \Delta z ( \tau_{yz}|_y - \tau_{yz}|_{y+\Delta y} ) \\
& + \Delta x \Delta y ( \tau_{zz}|_z - \tau_{zz}|_{z+\Delta z} ) \\
& + \Delta x \Delta y ( p|_z - p|_{z+\Delta z} ) + \rho g_z
\end{aligned}$$

Setiap suku dari persamaan ini dibagi dengan  $\Delta x \Delta y \Delta z$  sehingga didapat :

$$\begin{aligned}
\frac{\partial \rho v_z}{\partial t} &= \frac{(\rho v_x v_z|_x - \rho v_x v_z|_{x+\Delta x})}{\Delta x} \\
&+ \frac{(\rho v_y v_z|_y - \rho v_y v_z|_{y+\Delta y})}{\Delta y} \\
&+ \frac{(\rho v_z v_z|_z - \rho v_z v_z|_{z+\Delta z})}{\Delta z} \\
&+ \frac{(\tau_{xz}|_x - \tau_{xz}|_{x+\Delta x})}{\Delta x} \\
&+ \frac{(\tau_{yz}|_y - \tau_{yz}|_{y+\Delta y})}{\Delta y} \\
&+ \frac{(\tau_{zz}|_z - \tau_{zz}|_{z+\Delta z})}{\Delta z} \\
&+ \frac{(p|_z - p|_{z+\Delta z})}{\Delta z} + \rho g_z
\end{aligned}$$

Karena harga-harga dari  $\Delta x$   $\Delta y$   $\Delta z$  kecil sekali maka diambil harga limitnya untuk  $\Delta x$ ,  $\Delta y$ ,  $\Delta z$  mendekati nol, sehingga :

$$\begin{aligned} \frac{\partial p v_z}{\partial t} &= \lim_{\Delta x \rightarrow 0} \left( \frac{\rho v_x v_z|_x - \rho v_x v_z|_{x+\Delta x}}{\Delta x} \right) \\ &+ \lim_{\Delta y \rightarrow 0} \left( \frac{\rho v_y v_z|_y - \rho v_y v_z|_{y+\Delta y}}{\Delta y} \right) \\ &+ \lim_{\Delta z \rightarrow 0} \left( \frac{\rho v_z v_z|_z - \rho v_z v_z|_{z+\Delta z}}{\Delta z} \right) \\ &+ \lim_{\Delta x \rightarrow 0} \left( \frac{\tau_{xz}|_z - \tau_{xz}|_{x+\Delta x}}{\Delta x} \right) \\ &+ \lim_{\Delta y \rightarrow 0} \left( \frac{\tau_{yz}|_y - \tau_{yz}|_{y+\Delta y}}{\Delta y} \right) \\ &+ \lim_{\Delta z \rightarrow 0} \left( \frac{\tau_{zz}|_z - \tau_{zz}|_{z+\Delta z}}{\Delta z} \right) \\ &+ \lim_{\Delta z \rightarrow 0} \left( \frac{p|_z - p|_{z+\Delta z}}{\Delta z} \right) + \rho g_z \end{aligned}$$

maka :

$$\begin{aligned} \frac{\partial p v_z}{\partial t} &= - \left( \frac{\partial \rho v_x v_z}{\partial x} + \frac{\partial \rho v_y v_z}{\partial y} + \frac{\partial \rho v_z v_z}{\partial z} \right) \\ &- \frac{\partial \tau_{xz}}{\partial x} - \frac{\partial \tau_{yz}}{\partial y} - \frac{\partial \tau_{zz}}{\partial z} - \frac{\partial p}{\partial z} + \rho g_z \end{aligned}$$

atau :

$$\frac{\partial \rho v_z}{\partial t} + \frac{\partial \rho v_x v_z}{\partial x} + \frac{\partial \rho v_y v_z}{\partial y} + \frac{\partial \rho v_z v_z}{\partial z} = -\frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} - \frac{\partial p}{\partial z} + \rho g_z$$

Ruas kanan persamaan ini dideffrensialkan sehingga didapat :

$$\rho \left( \frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) + v_z \left( \frac{\partial \rho}{\partial t} + \frac{\partial v_x \rho}{\partial x} + \frac{\partial v_y \rho}{\partial y} + \frac{\partial v_z \rho}{\partial z} \right) = -\frac{\partial \tau_{xz}}{\partial x} - \frac{\partial \tau_{yz}}{\partial y} - \frac{\partial \tau_{zz}}{\partial z} - \frac{\partial p}{\partial z} + \rho g_z$$

Sesuai dengan persamaan Kontinuitas :

$$\frac{\partial \rho}{\partial t} + \frac{\partial v_x \rho}{\partial x} + \frac{\partial v_y \rho}{\partial y} + \frac{\partial v_z \rho}{\partial z} = 0$$

Sehingga didapat persamaan :

$$\rho \left( \frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial \tau_{xz}}{\partial x} - \frac{\partial \tau_{yz}}{\partial y} - \frac{\partial \tau_{zz}}{\partial z} - \frac{\partial p}{\partial z} + \rho g_z$$

dimana :

index pertama menyatakan arah perpindahan

index kedua menyatakan arah vektor

$v$  = kecepatan fluida

$p$  = gaya tekan ;  $g$  = gaya grafitasi

$\tau$  = tegangan geser ;  $t$  = waktu

Maka didapat persamaan gerak dalam 3 arah, yaitu :

Pada arah x :

$$\rho \left( \frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) =$$
$$- \left\{ \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} \right\} - \frac{\partial p}{\partial x} + \rho g_x$$

Pada arah y :

$$\rho \left( \frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) =$$
$$- \left\{ \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} \right\} - \frac{\partial p}{\partial y} + \rho g_y$$

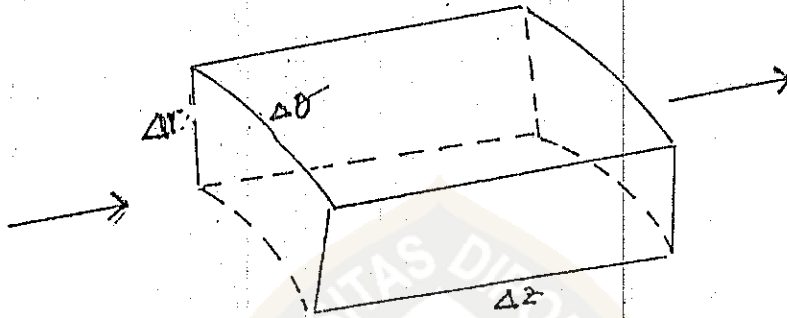
Pada arah z :

$$\rho \left( \frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) =$$
$$- \left\{ \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} \right\} - \frac{\partial p}{\partial z} + \rho g_z$$



### 3.4 GERAK ALIRAN FLUIDA DALAM PIPA

Sebuah pipa dialiri suatu fluida dengan kecepatan sebesar  $v$  untuk mendapatkan Model Matematik dari gerakan aliran tersebut diambil pipa dengan sisi-sisi  $\Delta r, \Delta x, \Delta \theta$  yang berkedudukan tetap dalam ruang, seperti tampak pada gambar :



Gambar III. yang ditinjau adalah perpindahan momentumnya, untuk menerapkan persamaan (3) diambil pengertian sbb:

$$\text{Luas} = \Delta r \Delta \theta$$

$$\text{Laju Alir Momentum masuk} = \rho V \cdot v \cdot \Delta r \Delta \theta$$

$$\text{Laju Alir Momentum keluar} = \rho V \cdot v \cdot \Delta r \Delta \theta$$

$$\text{Laju Akumulasi Momentum} = \Delta r \Delta \theta \rho V v_{\text{masuk}} - \Delta r \Delta \theta \rho V v_{\text{keluar}}$$

Dalam setiap fluida mengalir ada dua jenis perpindahan momentum

1. Perpindahan momentum secara molekuler, ditimbulkan karena gaya tarik menarik antar molekul dan arah perpindahan menuju ke semua arah koordinat.

2. Perpindahan momentum secara konveksi, juga menuju ke semua arah koordinat.

Penyebab perpindahan momentum ini adalah aliran masa, maka disebut perpindahan secara konveksi.

Kecepatan  $v_z$  dapat menimbulkan perpindahan momentum ke arah  $r$  yang fluksinya dinamakan  $\mathcal{J}_{rz}$ , juga ke arah  $\theta$  fluksinya  $\mathcal{J}_{\theta z}$  dan juga ke arah  $z$  fluksinya  $\mathcal{J}_{zz}$ .

Gaya-gaya yang bekerja pada unsur volume ada dua yakni gaya - tekanan dan gaya gravitasi.

Adanya selisih tekanan antara dua tempat didalam volume akan menimbulkan perubahan kecepatan maupun arahnya dan seterusnya-berakibat pada perubahan fluksi momentum, baik besar dan arahnya. Pada bentuk silinder masih ada satu gaya, yaitu gaya sentrifugal yang ditimbulkan oleh gerakan fluida ke arah  $\phi$ , baik secara konveksi maupun secara molekuler.

Mula -mula ditinjau komponen ke arah r (Catatan : indeks pertama menunjukkan arah perpindahan, indeks kedua arah vektor) melalui bidang  $\Delta\phi \Delta z$  berpindah secara :

$$\begin{aligned} \text{konveksi} & ; (\rho V_r V_r|_r - \rho V_r V_r|_{r+\Delta r}) r \Delta\phi \Delta z \\ \text{molekuler} & ; (\mathcal{J}_{rr}|_r - \mathcal{J}_{rr}|_{r+\Delta r}) r \Delta\phi \Delta z \end{aligned}$$

Melalui bidang  $\Delta\phi \Delta r$  berpindah secara :

$$\begin{aligned} \text{konveksi} & ; (\rho V_z V_r|_z - \rho V_z V_r|_{z+\Delta z}) r \Delta\phi \Delta z \\ \text{molekuler} & ; (\mathcal{J}_{zr}|_z - \mathcal{J}_{zr}|_{z+\Delta z}) r \Delta\phi \Delta z \end{aligned}$$

Melalui bidang  $\Delta r \Delta z$  berpindah secara :

$$\begin{aligned} \text{konveksi} & ; (\rho V_\phi V_r|_\phi - \rho V_\phi V_r|_{\phi+\Delta\phi}) \Delta r \Delta z \\ \text{molekuler} & ; (\mathcal{J}_{\phi r}|_\phi - \mathcal{J}_{\phi r}|_{\phi+\Delta\phi}) \Delta r \Delta z \end{aligned}$$

Perpindahan momentum oleh tekanan dan gaya gravitasi ke arah r

$$(p|_r - p|_{r+\Delta r}) r \Delta\phi \Delta z + \rho g_r r \Delta\phi \Delta r \Delta z$$

Gaya sentrifugal ke arah r ialah :

$$\frac{\rho V_\phi V_\phi}{r} r \Delta\phi \Delta r \Delta z + \frac{\mathcal{J}_{\phi\phi}}{r} r \Delta\phi \Delta r \Delta z$$

Laju akumulasi momentum kearah r, karena laju ini mengalami perubahan setiap perubahan waktu maka :

$$r \Delta \theta \Delta r \Delta z \cdot \lim_{\Delta t \rightarrow 0} \frac{(V_r, t + \Delta t) - (V_r, t)}{\Delta t} = r \Delta \theta \Delta r \Delta z \frac{\partial (\rho v_r)}{\partial t}$$

Apabila semua suku laju pindah momentum dijumlahkan sesuai persamaan ( 3 ) maka :

$$\begin{aligned} r \Delta \theta \Delta r \Delta z \frac{\partial (\rho v_r)}{\partial t} = & (\rho v_r v_r |_r - \rho v_r v_r |_{r+\Delta r}) r \Delta \theta \Delta z \\ & + (v_\theta v_r |_\theta - v_\theta v_r |_{\theta+\Delta \theta}) \Delta r \Delta z \\ & + (\rho v_z v_r |_z - \rho v_z v_r |_{z+\Delta z}) r \Delta \theta \Delta r \\ & + \frac{v_\theta v_\theta}{r} r \Delta \theta \Delta r \Delta z \\ & + (\tau_{rr} |_r - \tau_{rr} |_{r+\Delta r}) r \Delta \theta \Delta r \\ & + (\tau_{zr} |_z - \tau_{zr} |_{z+\Delta z}) r \Delta \theta \Delta r \\ & + (\tau_{\theta r} |_\theta - \tau_{\theta r} |_{\theta+\Delta \theta}) \Delta r \Delta z + \frac{\tau_{\theta\theta}}{r} r \Delta \theta \Delta r \Delta z \\ & + (p |_r - p |_{r+\Delta r}) r \Delta \theta \Delta z + \rho g_r r \Delta \theta \Delta r \Delta z \\ & \dots\dots\dots ( 13 ) \end{aligned}$$

Ruas kiri dan kanan persamaan ( 13 ) dibagi dengan  $r \Delta \theta \Delta r \Delta z$  maka didapat :

$$\begin{aligned} \frac{\partial \rho v_r}{\partial t} = & \frac{(\rho v_r v_r |_r - \rho v_r v_r |_{r+\Delta r})}{\Delta r} + \frac{(\rho v_\theta v_r |_\theta - \rho v_\theta v_r |_{\theta+\Delta \theta})}{\Delta \theta} \\ & + \frac{(\rho v_z v_r |_z - \rho v_z v_r |_{z+\Delta z})}{\Delta z} + \frac{v_\theta v_\theta}{r} + \frac{(\tau_{rr} |_r - \tau_{rr} |_{r+\Delta r})}{\Delta r} \end{aligned}$$

$$+ \frac{(\mathcal{J}_{zr}|_z - \mathcal{J}_{zr}|_{z+\Delta z})}{\Delta z} + \frac{(\mathcal{J}_{\theta r}|\theta - \mathcal{J}_{\theta r}|\theta+\Delta\theta)}{\Delta\theta}$$

$$+ \frac{(p|r - p|r+\Delta r)}{\Delta r} + \rho g_r$$

Kemudian diambil limit dari tiap suku pada waktu  $\Delta\theta$ ,  $\Delta r$  dan  $\Delta z$  mendekati 0, didapat :

$$\frac{\partial \rho V_r}{\partial t} = \lim_{\Delta r \rightarrow 0} \frac{(V_r V_r|_r - V_r V_r|r+\Delta r)}{\Delta r} + \lim_{\Delta\theta \rightarrow 0} \frac{(V_\theta V_r|\theta - V_\theta V_r|\theta+\Delta\theta)}{\Delta\theta}$$

$$+ \lim_{\Delta z \rightarrow 0} \frac{(V_z V_r|_z - V_z V_r|_z+\Delta z)}{\Delta z} + \frac{\mathcal{J}_\theta}{r}$$

$$+ \lim_{\Delta r \rightarrow 0} \frac{(\mathcal{J}_{rr}|_r - \mathcal{J}_{rr}|_r+\Delta r)}{\Delta r} + \lim_{\Delta z \rightarrow 0} \frac{(\mathcal{J}_{zr}|_z - \mathcal{J}_{zr}|_z+\Delta z)}{\Delta z}$$

$$+ \lim_{\Delta\theta \rightarrow 0} \frac{(\mathcal{J}_{\theta r}|\theta - \mathcal{J}_{\theta r}|\theta+\Delta\theta)}{\Delta\theta} + \frac{\mathcal{J}_{\theta\theta}}{r} + \lim_{\Delta r \rightarrow 0} \frac{(p|r - p|r+\Delta r)}{\Delta r}$$

$$+ \rho g_r$$

Sehingga :

$$\rho \cdot \frac{\partial V_r}{\partial t} = - \frac{\partial(\rho r V_r V_r)}{\partial r} - \frac{\partial(\rho V_z V_r)}{\partial z} - \frac{\partial(\rho V_\theta V_r)}{\partial \theta} + \frac{\rho V_\theta^2}{r} - \frac{\partial(r \mathcal{J}_{rr})}{r \partial r}$$

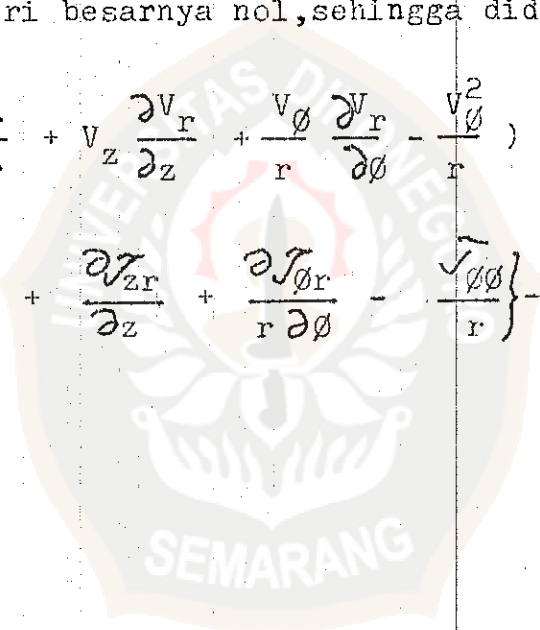
$$- \frac{\partial(\mathcal{J}_{zr})}{\partial z} - \frac{\partial(\mathcal{J}_{\theta r})}{r \partial \theta} + \frac{\mathcal{J}_{\theta\theta}}{r} - \frac{\partial p}{\partial r} + \rho g_r$$

Bila setiap suku yang memuat kecepatan dibawa ke ruas kiri dan dilakukan diferensi, dihasilkan :

$$v_r \left\{ \frac{\partial p}{\partial t} + \frac{\partial(\rho v_r)}{r \partial r} + \frac{\partial(\rho v_z)}{\partial z} + \frac{\partial(\rho v_\phi)}{\partial \phi} \right\} + \rho \left( \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + v_z \frac{\partial v_r}{\partial z} + \frac{v_\phi}{r} \frac{\partial v_r}{\partial \phi} - \frac{v_\phi^2}{r} \right) = - \left\{ \frac{\partial(r \tau_{rr})}{r \partial r} + \frac{\partial \tau_{zr}}{\partial z} + \frac{\partial \tau_{\phi r}}{r \partial \phi} - \frac{\tau_{\phi\phi}}{r} \right\} - \frac{\partial p}{\partial r} + \rho g_r$$

Berdasarkan persamaan Kontinuitas ( 12 ) maka kelompok suku pertama dalam ruas kiri besarnya nol, sehingga didapat bentuk :

$$\rho \left( \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + v_z \frac{\partial v_r}{\partial z} + \frac{v_\phi}{r} \frac{\partial v_r}{\partial \phi} - \frac{v_\phi^2}{r} \right) = - \left\{ \frac{\partial(r \tau_{rr})}{r \partial r} + \frac{\partial \tau_{zr}}{\partial z} + \frac{\partial \tau_{\phi r}}{r \partial \phi} - \frac{\tau_{\phi\phi}}{r} \right\} - \frac{\partial p}{\partial r} + \rho g_r \dots (14)$$



Komponen Momentum ke arah  $\theta$ .

Melalui bidang  $\Delta\theta\Delta z$ , berpindah secara :

$$\text{Konveksi : } (\rho v_r v_\theta|_r - \rho v_r v_\theta|_{r+\Delta r}) r \Delta\theta \Delta z$$

$$\text{Molekuler : } (\tau_{r\theta}|_r - \tau_{r\theta}|_{r+\Delta r})$$

Melalui bidang  $\Delta\theta\Delta r$ , berpindah secara :

$$\text{Konveksi : } (\rho v_z v_\theta - \rho v_z v_\theta) r \Delta\theta \Delta z$$

$$\text{Molekuler : } (\tau_{z\theta}|_\theta - \tau_{z\theta}|_{\theta+\Delta\theta}) r \Delta\theta \Delta z$$

Melalui bidang  $\Delta r\Delta z$ , berpindah secara :

$$\text{Konveksi : } (v_\theta v_\theta|_\theta - v_\theta v_\theta|_{\theta+\Delta\theta}) \Delta r \Delta z$$

$$\text{Molekuler : } (\tau_{\theta\theta}|_\theta - \tau_{\theta\theta}|_{\theta+\Delta\theta}) \Delta r \Delta z$$

Perpindahan Momentum oleh tekanan dan gaya gravitasi ke arah  $\theta$  :

$$(p|_\theta - p|_{\theta+\Delta\theta}) \Delta r \Delta z + \rho g_\theta \Delta r \Delta z$$

Gaya sentrifugal ke arah  $\theta$  ialah :

$$\left( \frac{v_\theta v_\theta}{r} + \frac{\tau_{r\theta}}{r} \right) \Delta z \cdot \Delta r$$

Laju Akumulasi momentum ke arah  $\theta$  :

$$r \cdot \Delta\theta \cdot \Delta r \cdot \Delta z \frac{\partial(\rho v_\theta)}{\partial t}$$

Berdasarkan persamaan ( 3 ), semua suku laju pindah momentum di susun, maka :

$$\begin{aligned} \Delta r \cdot \Delta\theta \cdot \Delta z \frac{\partial(\rho v_\theta)}{\partial t} &= (\rho v_r v_\theta|_r - \rho v_r v_\theta|_{r+\Delta r}) r \Delta\theta \Delta z \\ &+ (\rho v_z v_\theta|_z - \rho v_z v_\theta|_{z+\Delta z}) r \Delta\theta \Delta r + (\rho v_\theta v_\theta|_\theta - \rho v_\theta v_\theta|_{\theta+\Delta\theta}) r \Delta z \\ &+ (\tau_{r\theta}|_r - \tau_{r\theta}|_{r+\Delta r}) r \Delta\theta \Delta z + (\tau_{z\theta}|_z - \tau_{z\theta}|_{z+\Delta z}) r \Delta\theta \Delta r + (\tau_{\theta\theta}|_\theta \\ &- \tau_{\theta\theta}|_{\theta+\Delta\theta}) \Delta z \Delta r + \frac{\tau_{r\theta}}{r} r \cdot \Delta r \cdot \Delta\theta \cdot \Delta z \end{aligned}$$

\_\_\_\_\_ dibagi :

Maka ;

$$\frac{\partial(\rho V_\phi)}{\partial t} = \frac{(\rho V_r V_\phi | r - \rho V_r V_\phi | r + \Delta r)}{\Delta t}$$

$$+ \frac{(\rho V_t \cdot V_\phi | z - \rho V_t \cdot V_\phi | z + \Delta z)}{\Delta z}$$

$$+ \frac{(\rho V_\phi \cdot V_\phi | \phi - \rho V_\phi \cdot V_\phi | \phi + \Delta \phi)}{r \cdot \Delta \phi} + \frac{\rho V_r V_\phi}{r}$$

$$+ \frac{(\mathcal{J}_{r\phi} | r - \mathcal{J}_{r\phi} | r + \Delta r)}{\Delta r} + \frac{(\mathcal{J}_{z\phi} | z - \mathcal{J}_{z\phi} | z + \Delta z)}{r \Delta \phi} + \frac{\mathcal{J}_{r\phi}}{r}$$

Kemudian diambil harga limit pada saat  $\Delta r, \Delta z, \Delta \phi$  mendekati nol.

$$\frac{\partial \rho}{\partial t} = \lim_{\Delta r \rightarrow 0} \frac{(\rho V_r V_\phi | r - \rho V_r V_\phi | r + \Delta r)}{\Delta r}$$

$$+ \lim_{\Delta z \rightarrow 0} \frac{(\rho V_z V_\phi | z - \rho V_z V_\phi | z + \Delta z)}{\Delta z}$$

$$+ \lim_{\Delta \phi \rightarrow 0} \frac{(\rho V_\phi \cdot V_\phi | \phi - \rho V_\phi \cdot V_\phi | \phi + \Delta \phi)}{r \cdot \Delta \phi} + \frac{\rho V_r V_\phi}{r}$$

$$+ \lim_{\Delta r \rightarrow 0} \frac{(\mathcal{J}_{r\phi} | r - \mathcal{J}_{r\phi} | \phi + \Delta \phi)}{\Delta r}$$

$$+ \lim_{\Delta z \rightarrow 0} \frac{(\mathcal{J}_{z\phi} | z - \mathcal{J}_{z\phi} | z + \Delta z)}{\Delta z}$$

$$+ \lim_{\Delta \phi \rightarrow 0} \frac{(\mathcal{J}_{\phi\phi} | \phi - \mathcal{J}_{\phi\phi} | \phi + \Delta \phi)}{\phi \Delta \phi} + \frac{\mathcal{J}_{r\phi}}{r}$$

Maka ;

$$\frac{\partial V_\phi}{\partial t} = - \frac{\partial V_r \cdot V_\phi}{\partial r} - \frac{\partial V_z V_\phi}{\partial z} - \left( \frac{\partial V_\phi V_\phi}{r \partial \phi} + \frac{\partial V_r V_\phi}{\partial \phi} - \frac{\partial V_{r\phi}}{\partial r} \right)$$

$$- \frac{\partial \mathcal{J}_{z\phi}}{\partial z} - \frac{\partial \mathcal{J}_{\phi\phi}}{r \partial \phi} + \frac{\partial \mathcal{J}_{r\phi}}{\partial r}$$

Bila semua suku yang memuat kecepatan dibawa ke ruas kiri, maka :

$$\begin{aligned} \frac{\partial \rho V_\theta}{\partial t} + \frac{\partial \rho V_r}{\partial r} + \frac{\partial \rho V_z V_\theta}{\partial z} + \frac{1}{r} \frac{\partial \rho V_\theta V_\theta}{\partial \theta} - \frac{\partial \rho V_r V_\theta}{r} \\ = - \frac{\partial \tau_{r\theta}}{\partial r} - \frac{\tau_{z\theta}}{\partial z} - \frac{\partial \tau_{\theta\theta}}{r \partial \theta} + \frac{\tau_{r\theta}}{\partial r} \end{aligned}$$

Untuk ruas kiri dideferensi, maka ;

$$\begin{aligned} V_\theta \left\{ \frac{\partial \rho}{\partial t} + \frac{\partial V_r}{\partial r} + \frac{\partial V_z}{\partial z} + \frac{1}{r} \frac{\partial V_\theta}{\partial \theta} \right\} + \left\{ \frac{\partial V_\theta}{\partial t} + V_r \frac{\partial V_\theta}{\partial r} + V_z \frac{\partial V_\theta}{\partial z} + \right. \\ \left. \frac{V_\theta}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{V_r V_\theta}{r} \right\} = - \frac{1}{r} \frac{\partial \tau_{r\theta}}{\partial r} - \frac{\partial \tau_{z\theta}}{\partial z} - \frac{\partial \tau_{\theta\theta}}{r \partial \theta} + \frac{V_r \tau_{r\theta}}{r} \\ = - \frac{\partial \tau_{r\theta}}{\partial r} - \frac{\partial \tau_{z\theta}}{\partial z} - \frac{\partial \tau_{\theta\theta}}{r \partial \theta} + \frac{\tau_{r\theta}}{r} \dots \dots \dots (15) \end{aligned}$$

Laju Momentum ke arah z, melalui bidang  $\Delta\theta \Delta z$  berpindah secara ;

Konveksi :  $(\rho V_r \cdot V_z | r - \rho V_r \cdot V_z | r + \Delta r) r \cdot \Delta\theta \Delta r$

Molekuler :  $(\tau_{rz} | r - \tau_{rz} | r + \Delta r) r \Delta\theta \Delta r$

Melalui bidang  $\Delta\theta \cdot \Delta r$  berpindah secara ;

Konveksi :  $(\rho V_z \cdot V_z | z - \rho V_z \cdot V_z | z + \Delta z) r \Delta\theta \Delta z$

Molekuler :  $(\tau_{zz} | z - \tau_{zz} | z + \Delta z) r \Delta\theta \Delta z$

Melalui bidang  $\Delta r \Delta z$  berpindah secara ;

Konveksi ;  $(\rho V_\theta V_z | \theta - \rho V_\theta V_z | \theta + \Delta\theta) \Delta r \Delta z$

Molekuler :  $(\tau_{\theta z} | \theta - \tau_{\theta z} | \theta + \Delta\theta) \Delta r \cdot \Delta z$

Perpindahan momentum oleh tekanan dan gaya gravitasi ;

$$(\rho | z - \rho | z + \Delta z) r \Delta r \cdot \Delta\theta \Delta z + g_z r \Delta r \Delta\theta \Delta z$$

Gaya sentrifugal ke arah r ialah ;

$$\frac{V_r V_z}{r} r \Delta r \Delta\theta \Delta z + \frac{\tau_{\theta z}}{r} r \Delta r \Delta z \Delta\theta$$



Laju Akumulasi momentum ke arah z :

$$r \Delta r \Delta \phi \Delta z \frac{\partial p V_z}{\partial t}$$

Sesuai dengan persamaan ( 3 ) semua laju pindah momentum disusun, maka didapat bentuk :

$$\begin{aligned} r \Delta r \Delta \phi \Delta z \frac{\partial V_z}{\partial t} &= (\rho V_r V_z|_r - \rho V_r V_z|_{r+\Delta r}) r \Delta \phi \Delta z + (\rho V_\phi V_z|_\phi \\ &- \rho V_\phi V_z|_{\phi+\Delta \phi}) \Delta z \Delta r + (\rho V_z V_z|_z - \rho V_z V_z|_{z+\Delta z}) \\ &+ \frac{V_r V_z}{r} r \Delta r \Delta \phi \Delta z + (\bar{J}_{rz}|_r - \bar{J}_{rz}|_{r+\Delta r}) \\ &\cdot r \Delta \phi \Delta z + (\bar{J}_{\phi z}|_\phi + \bar{J}_{\phi z}|_{\phi+\Delta \phi}) \Delta r \Delta z \\ &+ (\bar{J}_{zz}|_z + \bar{J}_{zz}|_{z+\Delta z}) r \Delta \phi \Delta r \\ &+ (p|_z - p|_{z+\Delta z}) + \rho g_z \end{aligned}$$

\_\_\_\_\_ dibagi

oleh  $r \Delta r \Delta \phi \Delta z$  akan didapat

$$\begin{aligned} \frac{\partial p V_z}{\partial t} &= \frac{(\rho V_r V_z|_r - \rho V_r V_z|_{r+\Delta r})}{\Delta r} + \frac{(\rho V_\phi V_z|_z - \rho V_\phi V_z|_{z+\Delta z})}{r \Delta \phi} \\ &+ \frac{(\rho V_z V_z|_z - \rho V_z V_z|_{z+\Delta z})}{\Delta z} + \frac{V_r V_z}{r} + \frac{(\bar{J}_{rz}|_r - \bar{J}_{rz}|_{r+\Delta r})}{\Delta r} \\ &+ \frac{(\bar{J}_{\phi z}|_\phi - \bar{J}_{\phi z}|_{\phi+\Delta \phi})}{\Delta \phi} + \frac{(\bar{J}_{zz}|_z - \bar{J}_{zz}|_{z+\Delta z})}{\Delta z} \\ &+ \frac{(p|_z - p|_{z+\Delta z})}{\Delta z} + \rho g_z \end{aligned}$$

Kemudian diambil limit dari tiap suku pada saat  $\Delta r$ ,  $\Delta \phi$  dan  $\Delta z$  mendekati nol, maka didapat :

$$\begin{aligned} \frac{\partial \rho V_z}{\partial t} = & \lim_{\Delta r \rightarrow 0} \frac{(V_r V_z|_r - \rho V_r V_z|_{r+\Delta r})}{\Delta r} + \lim_{\Delta \phi \rightarrow 0} \frac{(\rho V_\phi V_z|_\phi - \rho V_\phi V_z|_{\phi+\Delta \phi})}{r \Delta \phi} \\ & + \lim_{\Delta z \rightarrow 0} \frac{(\rho V_z V_z|_z - \rho V_z V_z|_{z+\Delta z})}{\Delta z} + \lim_{\Delta r \rightarrow 0} \frac{(\sqrt{r z}|_r - \sqrt{r z}|_{r+\Delta r})}{\Delta r} \\ & + \lim_{\Delta \phi \rightarrow 0} \frac{(\sqrt{\phi z}|_\phi - \sqrt{\phi z}|_{\phi+\Delta \phi})}{\Delta \phi} + \lim_{\Delta z \rightarrow 0} \frac{(\sqrt{z z}|_z - \sqrt{z z}|_{z+\Delta z})}{\Delta z} \\ & + \lim_{\Delta z \rightarrow 0} \frac{(p|_z - p|_{z+\Delta z})}{\Delta z} + \frac{\rho V_r V_z}{r} + \rho g_z \end{aligned}$$

Bila setiap suku yang memuat kecepatan dibawa ke ruas kiri dan dilakukan diferensi, dihasilkan :

$$\begin{aligned} V_z \left\{ \frac{\partial \rho}{\partial t} + \frac{\partial (\rho V_r)}{\partial r} + \frac{\partial (\rho V_\phi)}{r \partial \phi} + \frac{\partial (\rho V_z)}{\partial z} \right\} + \rho \left( \frac{\partial V_z}{\partial t} + V_r \frac{\partial V_z}{\partial r} \right. \\ \left. + V_z \frac{\partial V_z}{\partial z} + \frac{V_\phi}{r} \frac{\partial V_z}{\partial \phi} \right) = - \left\{ \frac{\partial (\sqrt{r z})}{\partial r} + \frac{\partial \sqrt{z z}}{\partial z} + \frac{\partial \sqrt{\phi z}}{\partial \phi} \right\} \frac{\partial p}{\partial z} + \rho g_z \end{aligned}$$

berdasarkan persamaan Kontinuitas ( 12 ), maka kelompok suku pertama dalam ruas kiri besarnya nol, sehingga didapat bentuk :

$$\begin{aligned} \rho \left( \frac{\partial V_z}{\partial t} + V_r \frac{\partial V_z}{\partial r} + V_z \frac{\partial V_z}{\partial z} + \frac{V_\phi}{r} \frac{\partial V_z}{\partial \phi} \right) = - \frac{\partial (r \sqrt{r z})}{\partial r} + \frac{\partial \sqrt{z z}}{\partial z} \\ + \frac{\partial \sqrt{\phi z}}{r \partial \phi} - \frac{\partial p}{\partial z} + \rho g_z \dots \dots \dots (16) \end{aligned}$$

Persamaan-persamaan ( 14 ), ( 15 ), dan ( 16 ) adalah komponen ke- arah r,  $\theta$  dan z dari persamaan gerak dalam silinder yang dalam simbol vektor dituliskan sbb :

$$\rho \frac{D\vec{V}}{Dt} = - \nabla p - (\nabla \vec{J}) + \rho \vec{g} \dots\dots\dots ( 17 )$$

dimana :

$$\frac{D\vec{V}}{Dt} = \frac{\partial \vec{V}}{\partial t} + v_r \frac{\partial \vec{V}}{\partial r} + v_z \frac{\partial \vec{V}}{\partial z} + \frac{v_\theta}{r} \frac{\partial \vec{V}}{\partial \theta}$$

Suku-suku persamaan ( 17 ) mempunyai arti fisis sbb :

- $\vec{J}$  = laju pertambahan momentum oleh gesekan
- p = gya tekanan
- g = gaya gravitasi
- $\frac{D\vec{V}}{Dt}$  = laju pertambahan momentum per satuan volum

