

## BAB II

### DIFERENSIAL VEKTOR

#### II-1. GRADIEN ATAU SLOPE SUATU FUNGSI SKALAR.

Pandang sebuah fungsi skalar  $\phi ( u,v )$

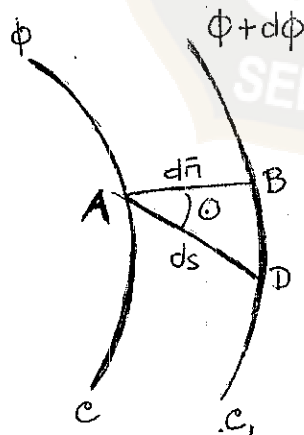
Kurva  $\phi ( u,v ) = \text{konstan}$  adalah kurva permukaan.

Ditentukan  $C$  dan  $C_1$  merupakan kurva permukaan yang berurutan sesuai dengan nilai-nilai  $\phi$  dan  $\phi + d\phi$  dari fungsi, dan  $d\phi$  adalah positif.

$AB$  merupakan elemen dari trayektori orthogonal dari kurva permukaan yang memotong  $C$  dan  $C_1$ ,  $|d\vec{n}|$  merupakan panjang elemen tersebut.

$AD$  adalah elemen yang lain, memotong  $C_1$  di  $D$ ,  $ds$  adalah panjang dari  $AD$ .

$AB$  merupakan jarak terpendek dari  $A$  kekurva  $C_1$  dan mempunyai arah perubahan  $\phi$  yang terbesar.



GB. 1.

Gradien dari  $\phi$  dititik  $A$  mempunyai arah  $AB$ ,

dan besarnya  $\frac{d\phi}{|d\vec{n}|}$

$$\text{Gradien } \phi = \vec{\nabla} \phi = \frac{d\phi}{|d\vec{n}|}$$

$$d\phi = (\text{grad } \phi) \cdot |d\vec{n}| = \vec{\nabla} \phi \cdot d\vec{n}$$

Karena  $\phi = \text{konstan}$ ,

$$d\phi = 0$$

grad  $\phi \neq 0$ ,  $d\bar{n} \neq 0$

grad  $\phi \perp d\bar{n}$

Nilai maksimum  $d\phi$  dihasilkan apabila grad  $\phi$  dan  $d\bar{n}$  berada dalam arah yang sama.

grad  $\phi // d\bar{n}$

$$d\phi = \nabla \phi \cdot |d\bar{n}|$$

Harga maksimum dari  $d\phi$  terjadi pada arah  $\nabla \phi$

Besarnya adalah  $|\nabla \phi| |d\bar{n}|$

Gradien  $\phi$  berada dalam arah perubahan  $\phi$  yang terbesar.

Hasil diatas dapat disimpulkan sebagai berikut:

- Vektor grad  $\phi$  pada sebarang titik, tegak lurus pada garis-garis atau permukaan yang untuknya  $\phi = \text{konstan}$ .
- Vektor grad  $\phi$  mempunyai arah perubahan  $\phi$  yang terbesar.

Jika  $\bar{m}$  = unit vektor pada arah AB, orthogonal pada  $\phi = \text{konstan}$ ,

$$\nabla \phi = \frac{d\phi}{d\bar{n}} \bar{m} \dots\dots\dots ( 2.1.1 )$$

Pertambahan dari kurva  $\phi$  pada arah AD:

$$\frac{d\phi}{ds} = \frac{d\phi}{d\bar{n}} \cdot \frac{d\bar{n}}{ds} = \frac{d\phi}{d\bar{n}} \cos \theta$$

$\theta$  = sudut inklinasi dari AD terhadap AB.

Kecepatan perubahan  $\phi$  dalam sebarang arah sepanjang permukaan dapat ditentukan dengan menggunakan vektor satuan dalam arah itu.

Jika  $\bar{a}$  = unit vektor pada arah AD,

$$\frac{d\phi}{ds} = \bar{a} \cdot \nabla \phi$$

disebut derivative dari  $\phi$  pada arah  $\bar{a}$  .

Jika  $d\bar{r}$  adalah vektor awal AD,

$$d\bar{r} = \bar{a} \cdot ds$$

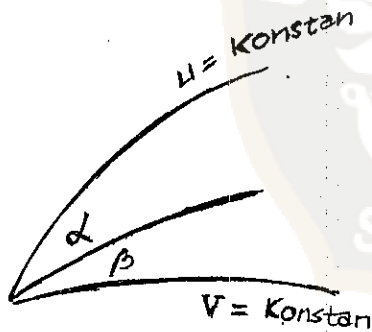
Perubahan  $d\phi$  dari fungsi karena perubahan  $d\bar{r}$  pada permukaan didapatkan dari:

$$d\phi = \frac{d\phi}{ds} \cdot ds$$

$$= ds ( \bar{a} \cdot \bar{\nabla} \phi )$$

$$d\phi = d\bar{r} \cdot \bar{\nabla} \phi \dots\dots\dots( 2.1.2 )$$

Gradien  $\phi$  bebas dari pemilihan parameternya, didapatkan rumusan untuk fungsi dengan koordinat  $u, v$  .



Pandang  $ds$  sebagai panjang pergeseran  $d\bar{r}$  sesuai dengan penambahan  $du, dv$  dan  $\delta s$  sebagai panjang pergeseran  $\delta\bar{r}$  yang lain sesuai penambahan  $\delta u, \delta v$  maka:

$$\begin{aligned} d\bar{r} &= \bar{r}_1 du + \bar{r}_2 dv \\ &= \frac{\partial \bar{r}}{\partial u} du + \frac{\partial \bar{r}}{\partial v} dv \end{aligned}$$

$$\begin{aligned} \delta\bar{r} &= \bar{r}_1 \delta u + \bar{r}_2 \delta v \\ &= \frac{\partial \bar{r}}{\partial u} \delta u + \frac{\partial \bar{r}}{\partial v} \delta v \end{aligned}$$

$\alpha$  = sudut antara kurva dan garis parameter  $u = \text{konstan}$

$\beta$  = sudut antara kurva dan garis parameter  $v = \text{konstan}$

$$\begin{aligned} ds \cdot \delta s \cos \beta &= d\bar{r} \cdot \delta\bar{r} \\ &= \bar{r}_1 \bar{r}_1 du \delta u + \bar{r}_1 \bar{r}_2 du \delta v + \bar{r}_2 \bar{r}_1 dv \delta u \\ &\quad + \bar{r}_2 \bar{r}_2 dv \delta v \end{aligned}$$

$$ds. \cos \beta = E du \delta u + F ( du \delta v + dv \delta u ) + G dv \delta v$$

Kedua arah saling tegak lurus jika:

$$\cos \beta = 0, \beta = \pi/2$$

$$E \frac{du}{dv} \frac{\delta u}{\delta v} + F \left( \frac{du}{dv} + \frac{\delta u}{\delta v} \right) + G = 0 \dots\dots\dots (2.1.3)$$

Persamaan diferensial trayektori orthogonal dari famili kelengkungan diberikan:

$$P \delta u + Q \delta v = 0$$

P, Q adalah fungsi dari u, v

$$\frac{\delta u}{\delta v} = - \frac{Q}{P}$$

$$E \frac{du}{dv} \left( - \frac{Q}{P} \right) + F \left\{ \frac{du}{dv} + \left( - \frac{Q}{P} \right) \right\} + G = 0$$

$$- EQ du + FP du - FQ dv + GP dv = 0$$

$$EQ du - FP du + FQ dv - GP dv = 0$$

$$( EQ - FP ) du + ( FQ - GP ) dv = 0$$

Pandang sekarang  $\phi (u, v) = \text{konstan}$

$$\phi_1 \delta u + \phi_2 \delta v = 0$$

Persamaan diferensial trayektori orthogonal didapatkan dengan mengambil:

$$P = \phi_1, Q = \phi_2$$

maka

$$( EQ_2 - FQ_1 ) du + ( FQ_2 - G\phi_1 ) dv = 0$$

$$\frac{du}{dv} = \frac{G\phi_1 - F\phi_2}{E\phi_2 - F\phi_1}$$

$$\text{vektor: } \vec{\mathcal{L}} = ( G\phi_1 - F\phi_2 ) \bar{r}_1 + ( E\phi_2 - F\phi_1 ) \bar{r}_2$$

menjadi paralel dengan  $\nabla \phi$

$$\frac{1}{\sqrt{E}} \bar{r}_1 \cdot \vec{\mathcal{L}} = ( G\phi_1 - F\phi_2 ) \frac{E}{\sqrt{E}} + ( E\phi_2 - F\phi_1 ) \frac{F}{\sqrt{E}}$$

$$\begin{aligned}
\frac{1}{\sqrt{E}} \bar{r}_1 \cdot \bar{\nabla} \phi &= \frac{EG\phi_1 - EF\phi_2}{\sqrt{E}} + \frac{EF\phi_2 - F^2\phi_1}{\sqrt{E}} \\
&= \frac{(EG - F^2)}{\sqrt{E}} \phi_1 \\
&= \frac{H^2}{\sqrt{E}} \phi_1 \\
&= H^2 \cdot \frac{1}{\sqrt{E}} \frac{\partial \phi}{\partial u}
\end{aligned}$$

merupakan  $H^2$  kali derivative  $\phi$  dengan arah  $\bar{r}_1$ .

Jadi gradien  $\phi$  adalah  $\frac{\bar{\nabla} \phi}{H^2}$

atau :

$$\bar{\nabla} \phi = \frac{(G\phi_1 - F\phi_2)}{H^2} \bar{r}_1 + \frac{(E\phi_2 - F\phi_1)}{H^2} \bar{r}_2 \quad \dots \dots \dots (2.14)$$

## II-2. BEBERAPA APLIKASI.

Gradien dari parameter  $u, v$  diperoleh dari:

$$\bar{\nabla} u = \frac{G}{H^2} \bar{r}_1 - \frac{F}{H^2} \bar{r}_2$$

$$\bar{\nabla} v = \frac{E}{H^2} \bar{r}_2 - \frac{F}{H^2} \bar{r}_1$$

karena:

$$\bar{\nabla} u \times \bar{\nabla} v = \frac{\bar{n}}{H} \quad \text{maka,}$$

$$(\bar{\nabla} u \times \bar{\nabla} v)^2 = \frac{1}{H^2}$$

$$(\bar{\nabla} u)^2 = \frac{G}{H^2} = G (\bar{\nabla} u \times \bar{\nabla} v)^2$$

$$\bar{\nabla} u \cdot \bar{\nabla} v = -\frac{F}{H^2} = -F (\bar{\nabla} u \times \bar{\nabla} v)^2$$

$$(\bar{\nabla} v)^2 = \frac{E}{H^2} = E (\bar{\nabla} u \times \bar{\nabla} v)^2$$

Bila kurva parametrik orthogonal,  $F = 0$ , maka:

$$(\bar{\nabla} u)^2 = \frac{G}{EG - F^2} = \frac{1}{E}$$

$$(\bar{\nabla} v)^2 = \frac{E}{EG - F^2} = \frac{1}{G}$$

### II-3. DIVERGEN VEKTOR.

Hasil kali skalar operator vektor  $\bar{\nabla}$  dengan sebuah fungsi vektor  $\bar{\alpha}$  ialah sebuah skalar diferensial invarian yang dinamakan: Divergen  $\bar{\alpha}$  atau  $\bar{\nabla} \cdot \bar{\alpha}$

$$\text{div } \bar{\alpha} = \bar{\nabla} \cdot \bar{\alpha}$$

$$\text{div } \bar{\alpha} = \frac{1}{H^2} \bar{r}_1 \left( G \frac{\partial \bar{\alpha}}{\partial u} - F \frac{\partial \bar{\alpha}}{\partial v} \right) + \frac{1}{H^2} \bar{r}_2 \left( E \frac{\partial \bar{\alpha}}{\partial v} - F \frac{\partial \bar{\alpha}}{\partial u} \right)$$

Untuk menyatakan pentingnya fungsi divergen, diambil divergensi dari unit normal  $\bar{n}$  pada permukaan.

$$\text{div } \bar{n} = \frac{1}{H^2} \bar{r}_1 ( G \bar{n}_1 - F \bar{n}_2 ) + \frac{1}{H^2} \bar{r}_2 ( E \bar{n}_2 - F \bar{n}_1 )$$

besaran order 2 :

$$L = \bar{n} \cdot \bar{r}_{11} \quad , \quad M = \bar{n} \cdot \bar{r}_{12} \quad , \quad N = \bar{n} \cdot \bar{r}_{22}$$

$\bar{n} \perp \bar{r}_1$ ,  $\bar{n} \perp \bar{r}_2$ ,  $\bar{n} \cdot \bar{r}_1 = 0$   
 didiferensialkan ke u:

$$\bar{n}_1 \bar{r}_1 + \bar{n} \bar{r}_{11} = 0$$

$$\bar{n}_1 \bar{r}_1 = -\bar{n}r_{11} = -L$$

$$\bar{n} \cdot \bar{r}_2 = 0$$

$$\bar{n}_1 \bar{r}_2 + \bar{n}r_{12} = 0$$

$$\bar{n}_1 \bar{r}_2 = -\bar{n}r_{12} = -M$$

$$\bar{n} \cdot \bar{r}_1 = 0$$

dideferensialkan ke v:

$$\bar{n}_2 \bar{r}_1 + \bar{n}r_{21} = 0$$

$$\bar{n}_2 \bar{r}_1 = -\bar{n}r_{21} = -M$$

$$\bar{n} \cdot \bar{r}_2 = 0$$

$$\bar{n}_2 \bar{r}_2 + \bar{n}r_{22} = 0$$

$$\bar{n}_2 \bar{r}_2 = -\bar{n}r_{22} = -N$$

dengan mensubstitusi  $\bar{n}_1$  &  $\bar{n}_2$  didapatkan:

$$\begin{aligned} \text{div } \bar{n} &= \frac{1}{H^2} ( -GL + FM ) + \frac{1}{H^2} ( -EN + FM ) \\ &= -\frac{1}{H^2} ( GL - FM + EN - FM ) \\ &= -\frac{1}{H^2} ( EN - 2FM + GL ) \end{aligned}$$

$$\text{div } \bar{n} = -\gamma \dots\dots\dots( 2.4.1 )$$

$\gamma$  = kelengkungan pertama

jadi kelengkungan pertama dari sebuah permukaan adalah negatif dari divergensi normal saruan.

Bila R merupakan sebuah skalar fungsi titik:

$$\bar{n} \perp \bar{r}_1, \bar{n} \perp \bar{r}_2$$

$$\text{div } R\bar{n} = R \text{ div } \bar{n}$$

$$\text{div } R\bar{n} = -\gamma R \dots\dots\dots ( 2.4.2 )$$

Kelengkungan pertama dari sebuah permukaan minimal adalah sama dengan nol,  $\gamma = 0$

$$\operatorname{div} \bar{n} = 0$$

$$\operatorname{div} R\bar{n} = 0$$

Divergen suatu vektor dapat dinyatakan dari hubungan beberapa komponen vektor.

$$\bar{\alpha} = P\bar{r}_1 + Q\bar{r}_2 + R\bar{n}$$

$$\operatorname{div} \bar{\alpha} = \operatorname{div} (P\bar{r}_1) + \operatorname{div} (Q\bar{r}_2) + \operatorname{div} (R\bar{n})$$

$$\begin{aligned} \operatorname{div} P\bar{r}_1 &= \frac{1}{H^2} \bar{r}_1 \left\{ G (P_1\bar{r}_1 + P\bar{r}_{11}) - F (P_2\bar{r}_1 + P\bar{r}_{12}) \right\} + \\ &\quad \frac{1}{H^2} \bar{r}_2 \left\{ E (P_2\bar{r}_1 + P\bar{r}_{12}) - F (P_1\bar{r}_1 + P\bar{r}_{11}) \right\} \\ &= \frac{1}{H^2} \left\{ GP_1\bar{r}_1\bar{r}_1 + GP\bar{r}_1\bar{r}_{11} - FP_2\bar{r}_1\bar{r}_1 - FP\bar{r}_1\bar{r}_{12} + \right. \\ &\quad \left. EP_2\bar{r}_1\bar{r}_2 + EP\bar{r}_2\bar{r}_{12} - FP_1\bar{r}_1\bar{r}_2 - FP\bar{r}_2\bar{r}_{11} \right\} \\ &= \frac{1}{H^2} \left\{ EGP_1 + GP\bar{r}_1\bar{r}_{11} - EFP_2 - FP\bar{r}_1\bar{r}_{12} + EFP_2 + \right. \\ &\quad \left. EP\bar{r}_2\bar{r}_{12} - F^2P_1 - FP\bar{r}_2\bar{r}_{11} \right\} \\ &= \frac{1}{H^2} \left\{ (EG - F^2)P_1 + P \left( G \frac{\partial \bar{r}}{\partial u} \frac{\partial^2 \bar{r}}{\partial u^2} + E \frac{\partial \bar{r}}{\partial v} \frac{\partial^2 \bar{r}}{\partial u \partial v} - \right. \right. \\ &\quad \left. \left. - F \frac{\partial \bar{r}}{\partial u} \frac{\partial^2 \bar{r}}{\partial u \partial v} - F \frac{\partial \bar{r}}{\partial v} \frac{\partial^2 \bar{r}}{\partial u^2} \right) \right\} \end{aligned}$$

diketahui bahwa:

$$\bar{r}_1 = \bar{r}_u$$

$$\bar{r}_2 = \bar{r}_v$$

$$E = \bar{r}_u \cdot \bar{r}_u$$

$$E_u = 2 \bar{r}_u \cdot \bar{r}_{uu}$$



$$\begin{aligned}\bar{r}_u \cdot \bar{r}_{uu} &= \frac{1}{2} E_u \\ &= \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_u)^2\end{aligned}$$

$$E_v = 2 \bar{r}_u \cdot \bar{r}_{uv}$$

$$\begin{aligned}\bar{r}_u \cdot \bar{r}_{uv} &= \frac{1}{2} E_v \\ &= \frac{1}{2} \frac{\partial}{\partial v} (\bar{r}_u)^2\end{aligned}$$

$$F = \bar{r}_u \cdot \bar{r}_v$$

$$\begin{aligned}F_u &= \bar{r}_{uu} \cdot \bar{r}_v + \bar{r}_u \cdot \bar{r}_{uv} \\ &= \bar{r}_v \cdot \bar{r}_{uu} + \frac{1}{2} E_v\end{aligned}$$

$$\begin{aligned}\bar{r}_v \cdot \bar{r}_{uu} &= F_u - \frac{1}{2} E_v \\ &= \frac{\partial}{\partial u} (\bar{r}_u \cdot \bar{r}_v) - \frac{1}{2} \frac{\partial}{\partial v} (\bar{r}_u)^2\end{aligned}$$

$$G = \bar{r}_v \cdot \bar{r}_v$$

$$G_u = 2 \bar{r}_v \cdot \bar{r}_{uv}$$

$$\begin{aligned}\bar{r}_v \cdot \bar{r}_{uv} &= \frac{1}{2} G_u \\ &= \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_v)^2\end{aligned}$$

$$\begin{aligned}\text{div } P\bar{F}_1 &= P_1 + \frac{P}{H^2} \left\{ G \frac{\partial}{\partial u} (\bar{r}_u)^2 + E \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_v)^2 - \right. \\ &\quad \left. - 2F \cdot \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_u \cdot \bar{r}_v)^2 \right\} \\ &= P_1 + \frac{P}{2H^2} \left\{ E \frac{\partial}{\partial u} (\bar{r}_2)^2 + G \frac{\partial}{\partial u} (\bar{r}_1)^2 - \right. \\ &\quad \left. - 2F \frac{\partial}{\partial u} (\bar{r}_1, \bar{r}_2) \right\}\end{aligned}$$

$$\operatorname{div} P\bar{F}_1 = P_1 + \frac{P}{2H^2} \left\{ E \frac{\partial}{\partial u} (G) + G \frac{\partial}{\partial u} (E) - 2F \frac{\partial}{\partial u} (F) \right\}$$

$$= P_1 + \frac{P}{2H^2} \frac{\partial}{\partial u} (2EG - 2F)$$

$$= P_1 + \frac{P}{H^2} \frac{\partial}{\partial u} (H^2)$$

$$\operatorname{div} P\bar{F}_2 = \frac{1}{H} \frac{\partial}{\partial u} (HP)$$

$$\operatorname{div} (Q\bar{F}_2) = \frac{1}{H^2} \bar{F}_1 \left\{ G (Q_1 \bar{F}_2 + Q\bar{F}_{12}) - F(Q_2 \bar{F}_1 + Q\bar{F}_{22}) \right\} +$$

$$+ \frac{1}{H^2} \bar{F}_2 \left\{ E (Q_2 \bar{F}_2 + Q\bar{F}_{22}) - F(Q_1 \bar{F}_2 + Q\bar{F}_{12}) \right\}$$

$$= \frac{1}{H^2} \left\{ GQ_1 \bar{F}_1 \bar{F}_2 + GQ\bar{F}_1 \bar{F}_{12} - FQ_2 \bar{F}_1 \bar{F}_2 - FQ\bar{F}_1 \bar{F}_{22} + \right. \\ \left. + EQ_2 \bar{F}_2 \bar{F}_2 + EQ\bar{F}_2 \bar{F}_{22} - FQ_1 \bar{F}_2 \bar{F}_2 - FQ\bar{F}_2 \bar{F}_{12} \right\}$$

$$\operatorname{div} (Q\bar{F}_2) = \frac{1}{H^2} (FGQ_1 + GQ\bar{F}_1 \bar{F}_{12} - F^2 Q_2 - FQ\bar{F}_1 \bar{F}_{22} +$$

$$+ EGQ_2 + EQ\bar{F}_2 \bar{F}_{22} - FQ_1 Q_1 - FQ\bar{F}_2 \bar{F}_{12})$$

$$= \frac{1}{H^2} \left\{ (EG - F^2) Q_2 \right\} + \frac{Q}{H^2} (E\bar{F}_2 \bar{F}_{22} +$$

$$+ G\bar{F}_1 \bar{F}_{12} - F\bar{F}_1 \bar{F}_{22} - F\bar{F}_2 \bar{F}_{12})$$

$$\bar{F}_1 = \bar{F}_u$$

$$\bar{F}_2 = \bar{F}_v$$

$$E = \bar{F}_u \cdot \bar{F}_u$$

$$E_v = 2\bar{F}_u \cdot \bar{F}_{uv}$$

$$\bar{F}_u \cdot \bar{F}_{uv} = \frac{1}{2} E_v$$

$$\bar{r}_u \cdot \bar{r}_{uv} = \frac{1}{2} \frac{\partial}{\partial v} (\bar{r}_u)^2$$

$$G = \bar{r}_v \cdot \bar{r}_v$$

$$G_v = 2 \bar{r}_v \cdot \bar{r}_{vv}$$

$$\bar{r}_v \cdot \bar{r}_{vv} = \frac{1}{2} G_v$$

$$= \frac{1}{2} \frac{\partial}{\partial v} (\bar{r}_v)^2$$

$$G_u = 2 \bar{r}_v \cdot \bar{r}_{uv}$$

$$\bar{r}_v \cdot \bar{r}_{uv} = \frac{1}{2} G_u$$

$$= \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_v)^2$$

$$F = \bar{r}_u \cdot \bar{r}_v$$

$$F_v = \bar{r}_{uv} \cdot \bar{r}_v + \bar{r}_u \cdot \bar{r}_{vv}$$

$$= \frac{1}{2} G_u + \bar{r}_u \cdot \bar{r}_{uv}$$

$$\bar{r}_u \cdot \bar{r}_{vv} = F_v - \frac{1}{2} G_u$$

$$= \frac{\partial}{\partial v} (\bar{r}_u \cdot \bar{r}_v) - \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_v)^2$$

$$\text{div} (Q\bar{r}_2) = Q_2 + \frac{Q}{H^2} \left( E \frac{\partial \bar{r}}{\partial v} \frac{\partial^2 \bar{r}}{\partial v^2} + G \frac{\partial \bar{r}}{\partial u} \frac{\partial^2 \bar{r}}{\partial u \partial v} - F \frac{\partial \bar{r}}{\partial u} \frac{\partial^2 \bar{r}}{\partial v^2} - \right.$$

$$\left. - F \frac{\partial \bar{r}}{\partial v} \frac{\partial^2 \bar{r}}{\partial u \partial v} \right)$$

$$= Q_2 + \frac{Q}{H^2} \left( E \cdot \frac{1}{2} \frac{\partial}{\partial v} (\bar{r}_v)^2 + G \cdot \frac{1}{2} \frac{\partial}{\partial v} (\bar{r}_u)^2 - \right.$$

$$\left. - F \frac{\partial}{\partial v} (\bar{r}_u \cdot \bar{r}_v) + F \cdot \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_v)^2 - \right.$$

$$\left. - F \cdot \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_v)^2 \right)$$

$$\begin{aligned}
\operatorname{div} ( Q \bar{F}_1 ) &= Q_2 + \frac{Q}{2H^2} \left\{ E \frac{\partial}{\partial v} ( \bar{F}_2 )^2 + G \frac{\partial}{\partial v} ( \bar{F}_1 )^2 - \right. \\
&\quad \left. - 2F \frac{\partial}{\partial v} ( \bar{F}_1 \cdot \bar{F}_2 ) \right\} \\
&= Q_2 + \frac{Q}{2H^2} \left\{ E \frac{\partial}{\partial v} ( G ) + G \frac{\partial}{\partial v} ( E ) - \right. \\
&\quad \left. - 2F \frac{\partial}{\partial v} ( F ) \right\} \\
&= Q_2 + \frac{Q}{2H^2} \frac{\partial}{\partial v} ( 2EG - 2F^2 ) \\
&= Q_2 + \frac{Q}{H^2} \frac{\partial}{\partial v} ( EG - F^2 ) \\
\operatorname{div} ( Q \bar{F}_2 ) &= Q_2 + \frac{Q}{H^2} \frac{\partial}{\partial v} ( H^2 )
\end{aligned}$$

$$\operatorname{div} ( Q \bar{F}_2 ) = \frac{1}{H} \frac{\partial}{\partial v} ( HQ )$$

diketahui dalam persamaan ( 2.4.2 ):

$$\operatorname{div} ( R \bar{n} ) = - J R$$

Jadi :

$$\operatorname{div} \bar{\mathcal{A}} = \frac{1}{H} \left\{ \frac{\partial}{\partial u} ( HP ) + \frac{\partial}{\partial v} ( HQ ) \right\} - J R$$

..... ( 2.4.3 )

Bila vektor  $\bar{\mathcal{A}}$  adalah sama dengan gradien fungsi skalar  $\phi$ , yaitu :

$$\begin{aligned}
\bar{\mathcal{A}} &= \bar{\nabla} \phi \\
\operatorname{div} \bar{\mathcal{A}} &= \operatorname{div} \bar{\nabla} \phi \\
&= \bar{\nabla} \cdot \bar{\nabla} \phi
\end{aligned}$$

$$\operatorname{div} \bar{\nabla} \phi = \bar{\nabla}^2 \phi$$

operator  $\bar{\nabla}^2$  disebut : operator Laplace atau Laplacian.

dari ( 2.1.4 )

$$\bar{\nabla} \phi = \frac{(G\phi_1 - F\phi_2)}{H^2} \bar{r}_1 + \frac{(E\phi_2 - F\phi_1)}{H^2} \bar{r}_2$$

Eliminasikan nilai-nilai P dan Q dari ( 2.1.4 ) pada persamaan ( 2.4.3 )

$$\bar{\nabla}^2 \phi = \frac{1}{H} \left\{ \frac{\partial}{\partial u} H \frac{(G\phi_1 - F\phi_2)}{H^2} + \frac{\partial}{\partial v} H \frac{(E\phi_2 - F\phi_1)}{H^2} \right\}$$

$$\bar{\nabla}^2 \phi = \frac{1}{H} \frac{\partial}{\partial u} \frac{(G\phi_1 - F\phi_2)}{H} + \frac{1}{H} \frac{\partial}{\partial v} \frac{(E\phi_2 - F\phi_1)}{H} \dots\dots ( 2.4.4 )$$

Bila kurva parametrik orthogonal :

$$F = 0$$

$$\bar{\nabla}^2 \phi = \frac{1}{\sqrt{EG}} \left\{ \frac{\partial}{\partial u} \left( \phi_1 \sqrt{\frac{G}{E}} \right) + \frac{\partial}{\partial v} \left( \phi_2 \sqrt{\frac{E}{G}} \right) \right\} \dots\dots ( 2.4.5 )$$

#### II-4. KURL SUATU VEKTOR.

Operator  $\bar{\nabla}$  yang digunakan untuk suatu fungsi vektor  $\bar{\alpha}$  memberikan suatu diferensial invarian vektor, disebut kurl atau Rotasi dari  $\bar{\alpha}$ .

Didefinisikan :

$$\text{kurl } \bar{\alpha} = \bar{\nabla} \times \bar{\alpha}$$

$$\text{kurl } \bar{\alpha} = \frac{1}{H^2} \bar{r}_1 \times \left( G \frac{\partial \bar{\alpha}}{\partial u} - F \frac{\partial \bar{\alpha}}{\partial v} \right) +$$

$$\frac{1}{H^2} \bar{r}_2 \times \left( E \frac{\partial \bar{\alpha}}{\partial v} - F \frac{\partial \bar{\alpha}}{\partial u} \right)$$

Ambil kurl dari suatu vektor  $R\bar{n}$  normal pada permukaan.

kaan.

$$\text{kurl } R\bar{n} = \frac{1}{H^2} \bar{r}_1 \times \left\{ G ( R_1\bar{n} + R\bar{n}_1 ) - F ( R_2\bar{n} + R\bar{n}_2 ) \right\} \\ + \frac{1}{H^2} \bar{r}_2 \times \left\{ E ( R_2\bar{n} + R\bar{n}_2 ) - F(R_1\bar{n}+R\bar{n}_1) \right\}$$

$$\text{kurl } R\bar{n} = \bar{\nabla} R \times \bar{n}$$

Jika  $R = \text{konstan}$ , maka

$$\bar{\nabla} R = 0$$

$$\text{kurl } R\bar{n} = 0$$

$$\text{kurl } \bar{n} = \bar{\nabla} \times \bar{n} = 0$$

$$\text{kurl } \bar{r} = \bar{\nabla} \times \bar{r} = 0$$

Jika :

$$\bar{\mathcal{L}} = P\bar{r}_1 + Q\bar{r}_2 + R\bar{n}$$

$$\text{kurl } \bar{\mathcal{L}} = \text{kurl } P\bar{r}_1 + \text{kurl } Q\bar{r}_2 + \text{kurl } R\bar{n}$$

$$\text{kurl } P\bar{r}_1 = \frac{1}{H^2} \bar{r}_1 \times \left\{ G ( P_1\bar{r}_1 + P\bar{r}_{11} ) - F ( P_2\bar{r}_1 + P\bar{r}_{12} ) \right\} +$$

$$\frac{1}{H^2} \bar{r}_2 \times \left\{ E ( P_2\bar{r}_1 + P\bar{r}_{12} ) - F(P_1\bar{r}_1 + P\bar{r}_{11}) \right\}$$

$$= \frac{1}{H^2} \bar{r}_1 \times G ( P_1\bar{r}_1 + P\bar{r}_{11} ) - \frac{1}{H^2} \bar{r}_1 \times F(P_2\bar{r}_1 +$$

$$P\bar{r}_{12} ) + \frac{1}{H^2} \bar{r}_2 \times E(P_2\bar{r}_1 + P\bar{r}_{12}) -$$

$$\frac{1}{H^2} \bar{r}_2 \times F ( P_1\bar{r}_1 + P\bar{r}_{11} )$$

$$= \frac{1}{H^2} \bar{r}_1 \times \bar{r}_2 \cdot \bar{r}_2 ( P_1\bar{r}_1 + P\bar{r}_{11} ) - \frac{1}{H^2} \bar{r}_1 \times$$

$$\bar{r}_1 \cdot \bar{r}_2 ( P_2\bar{r}_1 + P\bar{r}_{12} ) + \frac{1}{H^2} \bar{r}_2 \times \bar{r}_1 \cdot \bar{r}_1 ( P_2\bar{r}_1 +$$

$$P\bar{r}_{12} ) - \frac{1}{H^2} \bar{r}_2 \times \bar{r}_1 \cdot \bar{r}_2 ( P_1\bar{r}_1 + P\bar{r}_{11} )$$

$$= \frac{1}{H} \bar{n} \cdot \bar{r}_2 ( P_1\bar{r}_1 + P\bar{r}_{11} ) - \frac{1}{H} \bar{n} \cdot \bar{r}_1 ( P_2\bar{r}_1 + P\bar{r}_{12} )$$

$$+ \frac{1}{H} \bar{n} \cdot \bar{r}_1 ( P_2\bar{r}_1 + P\bar{r}_{12} ) - \frac{\bar{n} \cdot \bar{r}_2}{H} ( P_1\bar{r}_1 + P\bar{r}_{11} )$$

$$\begin{aligned} \text{kurl } P\bar{r}_1 &= \frac{\bar{n} \cdot \bar{r}_2 \cdot \bar{r}_1 \cdot P_1}{H} + \frac{\bar{n} \cdot \bar{r}_{11} \cdot \bar{r}_2 \cdot P}{H} - \frac{\bar{n} \cdot \bar{r}_1 \cdot \bar{r}_1 \cdot P_2}{H} - \frac{\bar{n} \cdot \bar{r}_1 \cdot \bar{r}_2 \cdot P}{H} + \\ &\frac{\bar{n} \cdot \bar{r}_1 \cdot P_2 \cdot \bar{r}_1}{H} + \frac{\bar{n} \cdot \bar{r}_1 \cdot P \cdot \bar{r}_{12}}{H} - \frac{\bar{n} \cdot \bar{r}_2 \cdot P_1 \cdot \bar{r}_1}{H} - \frac{\bar{n} \cdot \bar{r}_2 \cdot P \cdot \bar{r}_{11}}{H} \\ &= \frac{1}{H} ( \bar{n} \cdot P \cdot \bar{r}_2 \cdot \bar{r}_{11} - \bar{n} \cdot P \cdot \bar{r}_1 \cdot \bar{r}_{12} + \bar{n} \cdot P \cdot \bar{r}_1 \cdot \bar{r}_{12} - \bar{n} \cdot P \cdot \bar{r}_2 \cdot \bar{r}_{11} ) \end{aligned}$$

$$\bar{r}_2 \cdot \bar{r}_{11} = \frac{\partial}{\partial u} ( \bar{r}_1 \cdot \bar{r}_2 ) - \frac{1}{2} \frac{\partial}{\partial v} ( \bar{r}_1 \cdot \bar{r}_1 )$$

$$\bar{r}_1 \cdot \bar{r}_{12} = \frac{1}{2} \frac{\partial}{\partial v} ( \bar{r}_1 \cdot \bar{r}_1 )$$

$$\begin{aligned} \text{kurl } P\bar{r}_1 &= \frac{\bar{n} \cdot P}{H} \left\{ \frac{\partial}{\partial u} ( \bar{r}_1 \cdot \bar{r}_2 ) - \frac{1}{2} \frac{\partial}{\partial v} ( \bar{r}_1 \cdot \bar{r}_1 ) - \frac{1}{2} \frac{\partial}{\partial v} ( \bar{r}_1 \cdot \bar{r}_1 ) \right\} + \\ &\frac{P}{H} ( \bar{r}_1 \cdot \bar{r}_{12} \cdot \bar{n} - \bar{r}_2 \cdot \bar{r}_{11} \cdot \bar{n} ) \end{aligned}$$

Dengan substitusi nilai-nilai  $\bar{r}_{11}$  dan  $\bar{r}_{12}$ , dimana  $\bar{n} \cdot \bar{r}_{11} = L$ ,  $\bar{n} \cdot \bar{r}_{12} = M$  didapatkan:

$$\text{kurl } P\bar{r}_1 = \frac{1}{H} \left\{ \frac{\partial}{\partial u} (FP) - \frac{\partial}{\partial v} (EP) \right\} \bar{n} + \frac{P}{H} ( M\bar{r}_1 - L\bar{r}_2 )$$

$$\begin{aligned} \text{kurl } Q\bar{r}_2 &= \frac{1}{H^2} \bar{r}_1 \times \left\{ G ( Q_1 \bar{r}_2 + Q \cdot \bar{r}_{12} ) - F ( Q_2 \bar{r}_2 + Q \cdot \bar{r}_{22} ) \right\} \\ &+ \frac{1}{H^2} \bar{r}_2 \times \left\{ E ( Q_2 \bar{r}_2 + Q \cdot \bar{r}_{22} ) - F ( Q_1 \bar{r}_2 + Q \cdot \bar{r}_{12} ) \right\} \\ &= \frac{1}{H^2} \bar{r}_1 \times G ( Q_1 \bar{r}_2 + Q \cdot \bar{r}_{12} ) - \frac{1}{H^2} \bar{r}_1 \times F ( Q_2 \bar{r}_2 + Q \cdot \bar{r}_{22} ) + \\ &\frac{1}{H^2} \bar{r}_2 \times E ( Q_2 \bar{r}_2 + Q \cdot \bar{r}_{22} ) - \frac{1}{H^2} \bar{r}_2 \times F ( Q_1 \bar{r}_2 + \\ &Q \cdot \bar{r}_{12} ) \\ &= \frac{1}{H^2} \bar{r}_1 \times \bar{r}_2 \cdot \bar{r}_2 ( Q_1 \bar{r}_2 + Q \cdot \bar{r}_{12} ) - \frac{1}{H^2} \bar{r}_1 \times \bar{r}_1 \cdot \bar{r}_2 \\ &( Q_2 \bar{r}_2 + Q \cdot \bar{r}_{22} ) + \frac{1}{H^2} \bar{r}_2 \times \bar{r}_1 \cdot \bar{r}_1 ( Q_2 \bar{r}_2 + Q \cdot \bar{r}_{12} ) - \\ &\frac{1}{H^2} \bar{r}_2 \times \bar{r}_1 \cdot \bar{r}_2 ( Q_1 \bar{r}_2 + Q \cdot \bar{r}_{12} ) \end{aligned}$$

$$\begin{aligned}
\text{kurl } Q\bar{r}_2 &= \frac{1}{H} \bar{n} \cdot \bar{r}_2 (Q_1 \bar{r}_2 + Q\bar{r}_{12}) - \frac{1}{H} \bar{n} \cdot \bar{r}_1 (Q_2 \bar{r}_2 + Q\bar{r}_{22}) + \\
&\quad + \frac{1}{H} \bar{n} \cdot \bar{r}_1 (Q_2 \bar{r}_2 + Q\bar{r}_{22}) - \frac{1}{H} \bar{n} \cdot \bar{r}_2 (Q_1 \bar{r}_2 + Q\bar{r}_{12}) \\
&= \frac{\bar{n} \cdot \bar{r}_2}{H} Q_1 \bar{r}_2 + \frac{\bar{n} \cdot \bar{r}_2}{H} Q\bar{r}_{12} - \frac{\bar{n} \cdot \bar{r}_1}{H} Q_2 \bar{r}_2 - \frac{\bar{n} \cdot \bar{r}_1}{H} Q\bar{r}_{22} + \\
&\quad + \frac{\bar{n} \cdot \bar{r}_1}{H} Q_2 \bar{r}_2 + \frac{\bar{n} \cdot \bar{r}_1}{H} Q\bar{r}_{22} - \frac{\bar{n} \cdot \bar{r}_2}{H} Q_1 \bar{r}_2 - \frac{\bar{n} \cdot \bar{r}_2}{H} Q\bar{r}_{12} \\
&= \frac{\bar{n} \cdot \bar{r}_2}{H} Q\bar{r}_{12} - \frac{\bar{n} \cdot \bar{r}_1}{H} Q\bar{r}_{22} + \frac{\bar{n} \cdot \bar{r}_1}{H} Q\bar{r}_{22} - \frac{\bar{n} \cdot \bar{r}_2}{H} Q\bar{r}_{12}
\end{aligned}$$

diketahui bahwa:

$$\bar{r}_2 \cdot \bar{r}_{12} = \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_2 \cdot \bar{r}_2)$$

$$\bar{r}_1 \cdot \bar{r}_{22} = \frac{\partial}{\partial v} (\bar{r}_1 \cdot \bar{r}_2) - \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_2 \cdot \bar{r}_2)$$

$$\begin{aligned}
\text{kurl } Q\bar{r}_2 &= \frac{\bar{n}}{H} Q\bar{r}_2 \bar{r}_{12} + \frac{\bar{n}}{H} Q\bar{r}_1 \bar{r}_{22} + \frac{\bar{n} \cdot \bar{r}_{22}}{H} \bar{r}_1 Q - \frac{\bar{n} \cdot \bar{r}_{12}}{H} \bar{r}_2 Q \\
&= \frac{\bar{n} Q}{H} \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_2 \cdot \bar{r}_2) - \frac{\bar{n} Q}{H} \frac{\partial}{\partial v} (\bar{r}_1 \cdot \bar{r}_2) - \\
&\quad - \frac{\bar{n} Q}{H} \frac{1}{2} \frac{\partial}{\partial u} (\bar{r}_2 \cdot \bar{r}_2) + \frac{Q}{H} (N\bar{r}_1 - M\bar{r}_2) \\
&= \frac{\bar{n} Q}{H} \frac{\partial}{\partial u} (G) - \frac{\bar{n} Q}{H} \frac{\partial}{\partial v} (F) + \frac{Q}{H} (N\bar{r}_1 - M\bar{r}_2)
\end{aligned}$$

$$\begin{aligned}
\text{kurl } Q\bar{r}_2 &= \frac{1}{H} \left\{ \frac{\partial}{\partial u} (GQ) - \frac{\partial}{\partial v} (FQ) \right\} \bar{n} + \\
&\quad \frac{Q}{H} (N\bar{r}_1 - M\bar{r}_2)
\end{aligned}$$

$$\text{kurl } \bar{\omega} = \text{kurl } P\bar{r}_1 + \text{kurl } Q\bar{r}_2 + \text{kurl } R\bar{n}$$

$$= \frac{1}{H} \left\{ \frac{\partial}{\partial u} (FP) - \frac{\partial}{\partial v} (EP) \right\} \bar{n} +$$

$$\frac{P}{H} (M\bar{r}_1 - L\bar{r}_2) + \frac{1}{H} \left\{ \frac{\partial}{\partial u} (GQ) - \frac{\partial}{\partial v} (FQ) \right\} \bar{n} +$$



$$+ \frac{Q}{H} (N\bar{r}_1 - M\bar{r}_2) + \bar{\nabla} R \times \bar{n}$$

$$\begin{aligned} \text{kurl } \bar{\omega} &= \frac{1}{H} \left\{ \frac{\partial}{\partial u} (FP + GQ) - \frac{\partial}{\partial v} (EP + FQ) \right\} \bar{n} + \\ &\quad \frac{1}{H} (PM + QN) \bar{r}_1 - \frac{1}{H} (PL + QM) \bar{r}_2 + \\ &\quad (\bar{\nabla} R \times \bar{n}) \dots\dots\dots (2.5.1) \end{aligned}$$

bila  $\bar{\omega} = \bar{\nabla} \phi$

dan diketahui,

$$\bar{\nabla} \phi = \frac{(G\phi_1 - F\phi_2)}{H^2} \bar{r}_1 + \frac{(E\phi_2 - F\phi_1)}{H^2} \bar{r}_2 \dots\dots\dots (2.1.4)$$

$$\begin{aligned} \text{kurl } \bar{\omega} &= \text{kurl } \bar{\nabla} \phi \\ &= \bar{\nabla} \times \bar{\nabla} \phi \end{aligned}$$

dengan mensubstitusi nilai-nilai P dan Q dari persamaan (2.1.4) pada persamaan (2.5.1) didapat :

$$\begin{aligned} \text{kurl } \bar{\nabla} \phi &= \frac{1}{H} \left\{ \frac{\partial}{\partial u} \left( \frac{G\phi_1 - F\phi_2}{H^2} \right) F + \frac{\partial}{\partial u} G \left( \frac{E\phi_2 - F\phi_1}{H^2} \right) \right\} - \\ &\quad \frac{1}{H} \left\{ \frac{\partial}{\partial v} E \left( \frac{G\phi_1 - F\phi_2}{H^2} \right) + \frac{\partial}{\partial v} F \left( \frac{E\phi_2 - F\phi_1}{H^2} \right) \right\} \\ &= \frac{1}{H} \left\{ \frac{\partial}{\partial u} \left( \frac{GF\phi_1 - F^2\phi_2}{H^2} \right) + \frac{\partial}{\partial u} \left( \frac{EG\phi_2 - GF\phi_1}{H^2} \right) \right\} - \\ &\quad \frac{1}{H} \left\{ \frac{\partial}{\partial v} \left( \frac{EG\phi_1 - EF\phi_2}{H^2} \right) + \frac{\partial}{\partial v} \left( \frac{EF\phi_2 - F^2\phi_1}{H^2} \right) \right\} \\ &= \frac{1}{H} \left\{ \frac{\partial}{\partial u} \left( \frac{EG - F^2}{H^2} \right) \phi_2 - \frac{\partial}{\partial v} \left( \frac{EG - F^2}{H^2} \right) \phi_1 \right\} \\ &= \frac{1}{H} \frac{\partial}{\partial u} \phi_2 - \frac{1}{H} \frac{\partial}{\partial v} \phi_1 \end{aligned}$$

$$\text{kurl } \bar{\nabla} \phi = 0$$

Jadi kurl dari gradien fungsi skalar adalah tangensial pada permukaan.

## II - 5. FUNGSI VEKTOR.

Operator  $\bar{a} \cdot \bar{\nabla}$  diterapkan pada suatu fungsi vektor, dimana diketahui bahwa  $\bar{a} \cdot \bar{\nabla} \phi$  adalah derivative  $\phi$  pada arah  $\bar{a}$ .

$\bar{a}$  = unit vektor

$$\frac{d\phi}{ds} = \bar{a} \cdot \bar{\nabla} \phi$$

Derivative  $\bar{\alpha}$  pada arah  $\bar{a}$ ,

$$\begin{aligned} \bar{a} \cdot \bar{\nabla} \bar{\alpha} &= \frac{1}{H^2} \bar{a} \cdot \bar{r}_1 \left( G \frac{\partial \bar{\alpha}}{\partial u} - F \frac{\partial \bar{\alpha}}{\partial v} \right) + \\ &\quad \frac{1}{H^2} \bar{a} \cdot \bar{r}_2 \left( E \frac{\partial \bar{\alpha}}{\partial v} - F \frac{\partial \bar{\alpha}}{\partial u} \right) \end{aligned}$$

jika  $\bar{a} = \frac{\bar{r}_1}{\sqrt{E}}$ ,

$$\bar{a} \cdot \bar{\nabla} \bar{\alpha} = \frac{1}{H^2 \sqrt{E}} \left\{ E ( G \bar{\alpha}_1 - F \bar{\alpha}_2 ) + F ( E \bar{\alpha}_2 - F \bar{\alpha}_1 ) \right\}$$

$$= \frac{1}{H^2 \sqrt{E}} ( EG \bar{\alpha}_1 - EF \bar{\alpha}_2 + EF \bar{\alpha}_2 - F^2 \bar{\alpha}_1 )$$

$$= \frac{1}{H^2 \sqrt{E}} ( EG - F^2 ) \bar{\alpha}_1$$

$$\bar{a} \cdot \bar{\nabla} \bar{\alpha} = \frac{\bar{\alpha}_1}{\sqrt{E}} = \frac{1}{\sqrt{E}} \frac{\partial \bar{\alpha}}{\partial u}$$

Operator  $\bar{\nabla}^2$  dalam persamaan ( 2.4.4 ) dapat diterapkan pula pada vektor fungsi titik yang memberikan suatu invarian diferensial order kedua.

Akan dihitung nilai dari  $\bar{\nabla}^2 \bar{r}$ .

Dari persamaan ( 2.4.5 ) diketahui :

$$\bar{\nabla}^2 \phi = \frac{1}{\sqrt{EG}} \frac{\partial}{\partial u} \left( \phi_1 \sqrt{\frac{G}{E}} \right) + \frac{1}{\sqrt{EG}} \frac{\partial}{\partial v} \left( \phi_2 \sqrt{\frac{E}{G}} \right)$$

$$\bar{\nabla}^2 \bar{r} = \frac{1}{\sqrt{EG}} \frac{\partial}{\partial u} \left( \bar{r}_1 \sqrt{\frac{G}{E}} \right) + \frac{1}{\sqrt{EG}} \frac{\partial}{\partial v} \left( \bar{r}_2 \sqrt{\frac{E}{G}} \right)$$

$$\nabla^2 \bar{r} = \frac{1}{\sqrt{EG}} \left[ \left\{ \frac{\partial}{\partial u} \left( \sqrt{\frac{G}{E}} \right) \bar{r}_1 + \frac{\partial}{\partial u} \left( \bar{r}_1 \right) \sqrt{\frac{G}{E}} \right\} + \right. \\ \left. + \frac{\partial}{\partial v} \left( \sqrt{\frac{E}{G}} \right) \bar{r}_2 + \frac{\partial}{\partial v} \left( \bar{r}_2 \right) \sqrt{\frac{E}{G}} \right]$$

$$\nabla^2 \bar{r} = \frac{1}{\sqrt{EG}} \left\{ \bar{r}_1 \left( \frac{G_1}{2\sqrt{EG}} - \frac{E_1 \sqrt{G}}{2E\sqrt{E}} \right) + \sqrt{\frac{G}{E}} \bar{r}_{11} + \bar{r}_2 \left( \frac{E_2}{2\sqrt{EG}} - \frac{G_2 \sqrt{E}}{2G\sqrt{G}} \right) + \sqrt{\frac{E}{G}} \bar{r}_{22} \right\}$$

$$\nabla^2 \bar{r} = \frac{1}{\sqrt{EG}} \left\{ \sqrt{\frac{E}{G}} \left( \frac{G_1}{2E} \bar{r}_1 - \frac{G_2}{2G} \bar{r}_2 \right) + \sqrt{\frac{G}{E}} \left( \frac{E_2 \bar{r}_2}{2G} - \frac{E_1 \bar{r}_1}{2E} \right) + \right. \\ \left. \sqrt{\frac{G}{E}} \bar{r}_{11} + \sqrt{\frac{E}{G}} \bar{r}_{22} \right\}$$

dengan formula Gauss didapatkan harga  $\bar{r}_{11}$ ,  $\bar{r}_{22}$

$$\bar{r}_{11} = L\bar{n} + l\bar{r}_1 + \lambda\bar{r}_2$$

$$\bar{r}_{12} = M\bar{n} + m\bar{r}_1 + \mu\bar{r}_2$$

$$\bar{r}_{22} = N\bar{n} + k\bar{r}_1 + j\bar{r}_2$$

$$\bar{r}_1 \cdot \bar{r}_{11} = \frac{1}{2} E_1$$

$$\bar{r}_2 \cdot \bar{r}_{11} = F_1 - \frac{1}{2} E_2$$

$$\frac{1}{2} E_1 = l \cdot \bar{r}_1 \cdot \bar{r}_1 + \lambda \bar{r}_2 \cdot \bar{r}_1 = lE + \lambda F$$

$$F_1 - \frac{1}{2} E_2 = l \cdot \bar{r}_1 \cdot \bar{r}_2 + \lambda \bar{r}_2 \cdot \bar{r}_2 = lF + \lambda G$$

$$\frac{1}{2} E_1 G = lEG + \lambda GF \implies 1 \times G$$

$$FF_1 - \frac{1}{2} E_2 F = lF^2 + \lambda GF \implies 2 \times F$$

$$\frac{1}{2} E_1 G - FF_1 + \frac{1}{2} E_2 F = lH^2$$

$$l = \frac{1}{2H^2} (GE_1 - 2FF_1 + FE_2)$$

$$EF_1 - \frac{1}{2} EE_2 = lEF + \lambda EG \implies 2 \times E$$

$$\frac{1}{2} E_1 F - FF_1 = lEF + \lambda F^2 \implies 1 \times F$$

$$EF_1 - \frac{1}{2} EE_2 - \frac{1}{2} E_1 F = \lambda H^2$$

$$\lambda = \frac{1}{2H^2} ( 2EF_1 - EE_2 - FE_1 )$$

$$\bar{r}_1 \cdot \bar{r}_{22} = F_2 - \frac{1}{2}G_1$$

$$\bar{r}_2 \cdot \bar{r}_{22} = \frac{1}{2}G_2$$

$$F_2 - \frac{1}{2}G_1 = k \cdot \bar{r}_1 \cdot \bar{r}_1 + j \bar{r}_1 \cdot \bar{r}_2 = kE + jF$$

$$\frac{1}{2}G_2 = k \cdot \bar{r}_1 \cdot \bar{r}_2 + j \bar{r}_2 \cdot \bar{r}_2 = kF + jG$$

$$2 \times E \implies \frac{1}{2}G_2 E = k EF + jEG$$

$$1 \times F \implies \frac{FF_2 - \frac{1}{2}FG_1}{\frac{1}{2}EG_2 - FF_2 + \frac{1}{2}FG_1} = k EF + jF^2$$

$$\frac{1}{2}EG_2 - FF_2 + \frac{1}{2}FG_1 = jH^2$$

$$j = \frac{1}{2H^2} ( EG_2 - 2FF_2 + FG_1 )$$

$$1 \times G \implies GF_2 - \frac{1}{2}GG_1 = k \cdot EG + jFG$$

$$2 \times F \implies \frac{\frac{1}{2}FG_2}{GF_2 - \frac{1}{2}GG_1 - \frac{1}{2}FG_2} = k \cdot F^2 + jFG$$

$$GF_2 - \frac{1}{2}GG_1 - \frac{1}{2}FG_2 = kH^2$$

$$k = \frac{1}{2H^2} ( 2GF_2 - GG_1 - FG_2 )$$

karena kurva parametrik orthogonal,

$$F = 0$$

$$H^2 = EG$$

$$\bar{r}_{11} = L\bar{n} + \frac{E_1}{2E} \bar{r}_1 - \frac{E_2}{2G} \bar{r}_2$$

$$\bar{r}_{22} = N\bar{n} - \frac{G_1}{2E} \bar{r}_1 + \frac{G_2}{2G} \bar{r}_2$$

$$\nabla^2 \bar{r} = \frac{1}{\sqrt{EG}} \left\{ \sqrt{\frac{E}{G}} \left( \frac{G_1}{2E} \bar{r}_1 - \frac{G_2}{2G} \bar{r}_2 \right) + \sqrt{\frac{G}{E}} \left( \frac{E_2}{2G} \bar{r}_2 - \frac{E_1}{2E} \bar{r}_1 \right) \right.$$

$$\left. + \sqrt{\frac{G}{E}} \left( L\bar{n} + \frac{E_1}{2E} \bar{r}_1 - \frac{E_2}{2G} \bar{r}_2 \right) + \sqrt{\frac{E}{G}} \left( N\bar{n} - \frac{G_1}{2E} \bar{r}_1 + \frac{G_2}{2G} \bar{r}_2 \right) \right\}$$

$$\nabla^2 \bar{r} = \frac{L}{E} \bar{n} + \frac{N}{G} \bar{n} = \left( \frac{L}{E} + \frac{N}{G} \right) \bar{n}$$

$$\nabla^2 \bar{r} = j \bar{n} \quad \dots\dots (2.6.1)$$

diketahui (2.4.2),

$$\text{div } R\bar{n} = R \cdot \text{div } \bar{n} = -jR$$

$$\begin{aligned} \nabla \cdot \nabla^2 \bar{r} &= \nabla \cdot j \bar{n} \\ &= j \nabla \cdot \bar{n} \end{aligned}$$

$$\nabla \cdot \nabla^2 \bar{r} = -j^2$$

## II-6. RUMUS - RUMUS DIFERENSIASI.

Bila  $\phi$  sebuah fungsi skalar dan  $\bar{A}$ ,  $\bar{B}$  fungsi - fungsi vektor, dengan penguraian langsung, persamaan - persamaan dibawah ini dapat dibuktikan :

$$\nabla \cdot (\phi \bar{A}) = \nabla \phi \cdot \bar{A} + \phi \nabla \cdot \bar{A} \quad \dots\dots (1)$$

$$\nabla \times (\phi \bar{A}) = \nabla \phi \times \bar{A} + \phi \nabla \times \bar{A} \quad \dots\dots (2)$$

$$\nabla \cdot (\bar{A} \times \bar{B}) = \bar{B} \cdot \nabla \times \bar{A} - \bar{A} \cdot \nabla \times \bar{B} \quad \dots (3)$$

Akan dibuktikan persamaan-persamaan diatas dengan operator diferensial vektorial dan dengan mengambil kurva

parametrik orthogonal,

$$F = 0$$

$$H^2 = EG$$

$$\nabla = \frac{1}{E} \bar{r}_1 \frac{\partial}{\partial u} + \frac{1}{G} \bar{r}_2 \frac{\partial}{\partial v}$$

bukti :

$$1. \nabla \cdot (\phi \bar{A}) = \frac{1}{E} \bar{r}_1 \frac{\partial}{\partial u} (\phi \bar{A}) + \frac{1}{G} \bar{r}_2 \frac{\partial}{\partial v} (\phi \bar{A})$$

$$= \frac{1}{E} \bar{r}_1 (\phi_1 \bar{A} + \phi \bar{A}_1) + \frac{1}{G} \bar{r}_2 (\phi_2 \bar{A} + \phi \bar{A}_2)$$

$$= \left( \frac{1}{E} \bar{r}_1 \phi_1 + \frac{1}{G} \bar{r}_2 \phi_2 \right) \cdot \bar{A} + \phi \left( \frac{1}{E} \bar{r}_1 \bar{A}_1 + \right.$$

$$\left. \frac{1}{G} \bar{r}_2 \bar{A}_2 \right)$$

$$\nabla \cdot (\phi \bar{A}) = \nabla \phi \cdot \bar{A} + \phi \nabla \cdot \bar{A}$$

$$\begin{aligned}
 2. \quad \bar{\nabla} \times (\phi \bar{A}) &= \frac{1}{E} \bar{r}_1 \times \frac{\partial}{\partial u} (\phi \bar{A}) + \frac{1}{G} \bar{r}_2 \times \frac{\partial}{\partial v} (\phi \bar{A}) \\
 &= \frac{1}{E} \bar{r}_1 \times (\phi_1 \bar{A} + \phi \bar{A}_1) + \frac{1}{G} \bar{r}_2 \times (\phi_2 \bar{A} + \phi \bar{A}_2) \\
 &= \left( \frac{1}{E} \bar{r}_1 \cdot \phi_1 + \frac{1}{G} \bar{r}_2 \cdot \phi_2 \right) \times \bar{A} + \\
 &\quad \left( \frac{1}{E} \bar{r}_1 \times \bar{A}_1 + \frac{1}{G} \bar{r}_2 \times \bar{A}_2 \right) \phi
 \end{aligned}$$

$$\bar{\nabla} \times (\phi \bar{A}) = \bar{\nabla} \phi \times \bar{A} + \phi (\bar{\nabla} \times \bar{A})$$

$$\begin{aligned}
 3. \quad \bar{\nabla} (\bar{A} \times \bar{B}) &= \frac{1}{E} \bar{r}_1 \cdot \frac{\partial}{\partial u} (\bar{A} \times \bar{B}) + \frac{1}{G} \bar{r}_2 \cdot \frac{\partial}{\partial v} (\bar{A} \times \bar{B}) \\
 &= \frac{1}{E} \bar{r}_1 (\bar{A}_1 \times \bar{B} + \bar{A} \times \bar{B}_1) + \\
 &\quad \frac{1}{G} \bar{r}_2 (\bar{A}_2 \times \bar{B} + \bar{A} \times \bar{B}_2)
 \end{aligned}$$

$$\begin{aligned}
 \bar{\nabla} \cdot (\bar{A} \times \bar{B}) &= \left( \frac{1}{E} \bar{r}_1 \times \bar{A}_1 + \frac{1}{G} \bar{r}_2 \times \bar{A}_2 \right) \cdot \bar{B} - \\
 &\quad \left( \frac{1}{E} \bar{r}_1 \times \bar{B}_1 + \frac{1}{G} \bar{r}_2 \times \bar{B}_2 \right) \cdot \bar{A}
 \end{aligned}$$

$$\bar{\nabla} \cdot (\bar{A} \times \bar{B}) = \bar{B} \cdot \bar{\nabla} \times \bar{A} - \bar{A} \cdot \bar{\nabla} \times \bar{B}$$

Sebagai contoh diterapkan (1) dan (2) pada fungsi  $R\bar{n}$

$$- \operatorname{div} R\bar{n} = \bar{\nabla} R \cdot \bar{n} = \bar{\nabla} R \cdot \bar{n} + R \bar{\nabla} \cdot \bar{n}$$

$$\bar{\nabla} R \perp \bar{n}, \operatorname{div} \bar{n} = -j$$

$$\operatorname{div} R\bar{n} = -jR$$

$$- \operatorname{kurl} R\bar{n} = \bar{\nabla} \times R\bar{n}$$

$$= \bar{\nabla} R \times \bar{n} + R \bar{\nabla} \times \bar{n}$$

$$\operatorname{kurl} \bar{n} = 0$$

$$\operatorname{kurl} R\bar{n} = \bar{\nabla} R \times \bar{n}$$

$$- \operatorname{div} \operatorname{kurl} R\bar{n} = \operatorname{div} (\bar{\nabla} R \times \bar{n})$$

$$\begin{aligned} \text{div kurl } \bar{R}\bar{n} &= \bar{\nabla} \cdot (\bar{\nabla} R \times \bar{n}) \\ &= \bar{n} \cdot \bar{\nabla} \times \bar{\nabla} R - \bar{\nabla} R \cdot \bar{\nabla} \times \bar{n} \end{aligned}$$

$$\text{div kurl } \bar{R}\bar{n} = 0 \quad \dots\dots\dots (2.7.1)$$

Contoh :

1. Perhatikan bahwa :  $\text{div } \bar{F} = 2$

- kurva parametrik orthogonal,

$$\begin{aligned} \text{div } \bar{r} &= \frac{1}{E} \bar{r}_1 \frac{\partial}{\partial u} (\bar{r}) + \frac{1}{G} \bar{r}_2 \frac{\partial}{\partial v} (\bar{r}) \\ &= \frac{1}{E} \bar{r}_1 \cdot \bar{r}_1 + \frac{1}{G} \bar{r}_2 \cdot \bar{r}_2 \end{aligned}$$

$$\text{div } \bar{r} = \frac{E}{E} + \frac{G}{G} = 2$$

2. Perhatikan :  $\text{div } \gamma \bar{r} = \bar{r} \cdot \bar{\nabla} \gamma + 2\gamma$   
 $\text{kurl } \gamma \bar{r} = \bar{\nabla} \gamma \times \bar{r}$

Penyelesaian :

$$\begin{aligned} \text{div } \gamma \bar{r} &= \bar{\nabla} \cdot (\gamma \bar{r}) \\ &= \bar{\nabla} \gamma \cdot \bar{r} + \gamma \cdot \bar{\nabla} \bar{r} \end{aligned}$$

$$\text{div } \gamma \bar{r} = \bar{r} \cdot \bar{\nabla} \gamma + 2\gamma$$

$$\begin{aligned} \text{kurl } \gamma \bar{r} &= \bar{\nabla} \times \gamma \bar{r} \\ &= \bar{\nabla} \gamma \times \bar{r} + \gamma \cdot \bar{\nabla} \times \bar{r} \\ &= \bar{\nabla} \gamma \times \bar{r} + 0 \end{aligned}$$

$$\text{kurl } \gamma \bar{r} = \bar{\nabla} \gamma \times \bar{r}$$

3. Perhatikan :  $\bar{\nabla} (\phi \psi) = \phi \bar{\nabla} \psi + \psi \bar{\nabla} \phi$

Penyelesaian :

$$\begin{aligned} \bar{\nabla} (\phi \psi) &= \frac{1}{E} \bar{r}_1 (\phi_1 \psi + \phi \psi_1) + \frac{1}{G} \bar{r}_2 \\ & \quad (\phi_2 \psi + \phi \psi_2) \end{aligned}$$

$$= \left( \frac{1}{E} \bar{r}_1 \phi_1 + \frac{1}{G} \bar{r}_2 \phi_2 \right) \psi +$$

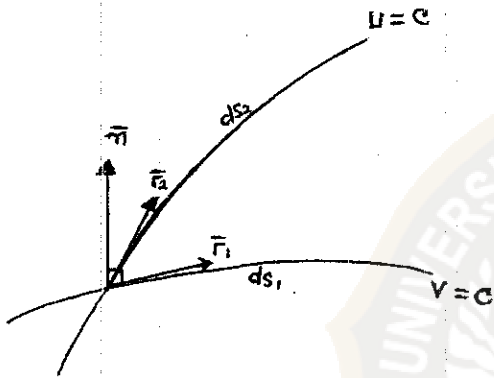
$$\phi \left( \frac{1}{E} \bar{r}_1 \psi_1 + \frac{1}{G} \bar{r}_2 \psi_2 \right)$$

$$\nabla(\phi\psi) = \nabla\phi\psi + \phi\nabla\psi$$

$$\nabla(\phi\psi) = \phi\nabla\psi + \psi\nabla\phi$$

## II - 7. KELENGKUNGAN GEODETIK .

Ditentukan sistim orthogonal dari kurva parameter,  $\bar{a}, \bar{b}$  adalah unit vektor pada arah  $\bar{r}_1$  dan  $\bar{r}_2$



$$\bar{r}_1 = \bar{r}_u, \quad \bar{r}_2 = \bar{r}_v$$

elemen garis :

$$ds^2 = Edu^2 + 2Fdudv + Gdv^2$$

elemen garis pada  $v=c$

$$ds^2 = Edu^2$$

$$ds_1 = \sqrt{E} du$$

$$\frac{ds_1}{du} = |\bar{r}_1| = \sqrt{E}$$

$$\text{maka: } \bar{a} = \frac{\bar{r}_1}{\sqrt{E}}$$

elemen garis pada  $u=c$

$$ds_2 = \sqrt{G} dv$$

$$\frac{ds_2}{dv} = |\bar{r}_2| = \sqrt{G}$$

$$\bar{b} = \frac{\bar{r}_2}{\sqrt{G}}$$

$\bar{a}, \bar{b}, \bar{n}$  membentuk sistim putar kanan :

$$\bar{a} \times \bar{b} = \bar{n}$$

$$\bar{b} \times \bar{n} = \bar{a}$$

$$\bar{n} \times \bar{a} = \bar{b}$$

Vektor kelengkungan dari kurva parameter  $v = \text{konstan}$ ,

$$\bar{K} = \frac{1}{\sqrt{E}} \frac{\partial \bar{a}}{\partial u}$$

$$\frac{\partial \bar{a}}{\partial u} = \frac{\partial}{\partial u} \left( \frac{\bar{r}_1}{\sqrt{E}} \right) = \frac{1}{\sqrt{E}} \bar{r}_{1u} - \frac{E_u}{2E\sqrt{E}} \bar{r}_1$$



$\bar{r}_{11}$  dihitung terlebih dahulu :

$$\bar{r}_{11} = L\bar{n} + l\bar{r}_1 + \lambda \bar{r}_2$$

$$\bar{r}_{12} = M\bar{n} + m\bar{r}_1 + \mu \bar{r}_2$$

diketahui bahwa :

$$\bar{r}_1 \cdot \bar{r}_{11} = \frac{1}{2} E_1$$

$$\bar{r}_2 \cdot \bar{r}_{11} = F_1 - \frac{1}{2} E_2$$

$$\bar{r}_1 \cdot \bar{r}_{11} = (L\bar{n} + l\bar{r}_1 + \lambda \bar{r}_2) \bar{r}_1$$

$$\bar{r}_1 \cdot \bar{r}_{11} = lE + \lambda F = \frac{1}{2} E_1$$

$$\bar{r}_2 \cdot \bar{r}_{11} = (L\bar{n} + l\bar{r}_1 + \lambda \bar{r}_2) \bar{r}_2$$

$$\bar{r}_2 \cdot \bar{r}_{11} = lF + \lambda G = F_1 - \frac{1}{2} E_2$$

$$1 \times F \implies lEF + \lambda F^2 = \frac{1}{2} E_1 F$$

$$2 \times E \implies lEF + \lambda EG = EF_1 - \frac{1}{2} EE_2$$

$$\lambda (EG - F^2) = EF_1 - \frac{1}{2} EE_2 - \frac{1}{2} E_1 F$$

$$\lambda = \frac{1}{2H^2} (2EF_1 - EE_2 - FE_1)$$

$$1 \times G \implies lEG + \lambda FG = \frac{1}{2} E_1 G$$

$$2 \times F \implies lF^2 + \lambda FG = FF_1 - \frac{1}{2} E_2 F$$

$$1 (EG - F^2) = \frac{1}{2} E_1 G - FF_1 + \frac{1}{2} FE_2$$

$$1 = \frac{1}{2H^2} (GE_1 - 2FF_1 + FE_2)$$

juga diketahui bahwa :

$$\bar{r}_1 \cdot \bar{r}_{12} = \frac{1}{2} E_2$$

$$\bar{r}_2 \cdot \bar{r}_{12} = \frac{1}{2} G_1$$

$$\bar{r}_1 \cdot \bar{r}_{12} = (M\bar{n} + m\bar{r}_1 + \mu \bar{r}_2) \bar{r}_1$$

$$= mE + \mu F = \frac{1}{2} E_2$$

$$\bar{r}_2 \cdot \bar{r}_{12} = (M\bar{n} + m\bar{r}_1 + \mu \bar{r}_2) \bar{r}_2$$

$$= mF + \mu G = \frac{1}{2} G_1$$

$$3 \times F \implies mEF + \mu F^2 = \frac{1}{2} E_2 F$$

$$4 \times E \implies mEF + \mu EG = \frac{1}{2} EG_1$$

$$\mu (EG - F^2) = \frac{1}{2} (EG_1 - E_2 F)$$

$$\mathcal{M} = \frac{1}{2H^2} (EG_1 - FE_2)$$

$$3 \times G \implies mEG + \mathcal{M}FG = \frac{1}{2}E_2G$$

$$4 \times F \implies \underline{mF^2 + \mathcal{M}FG = \frac{1}{2}FG_1 -}$$

$$m(EG - F^2) = \frac{1}{2}(GE_2 - FG_1)$$

$$m = \frac{1}{2H^2} (GE_2 - FG_1)$$

karena kurva parameter orthogonal :

$$F = 0$$

$$H^2 = EG \text{ maka :}$$

$$\bar{r}_1 = L\bar{n} + \frac{E_1}{2E} \bar{r}_1 - \frac{E_2}{2G} \bar{r}_2$$

$$\bar{r}_{1,2} = M\bar{n} + \frac{E_2}{2E} \bar{r}_1 + \frac{G_1}{2G} \bar{r}_2$$

$$\frac{\partial \bar{a}}{\partial u} = \frac{1}{\sqrt{E}} \left( L\bar{n} + \frac{E_1}{2E} \bar{r}_1 - \frac{E_2}{2G} \bar{r}_2 \right) - \frac{E_1 \bar{r}_1}{2E\sqrt{E}}$$

$$= \frac{L\bar{n}}{\sqrt{E}} + \frac{E_1}{2E\sqrt{E}} \bar{r}_1 - \frac{E_2}{2G\sqrt{E}} \bar{r}_2 - \frac{E_1 \bar{r}_1}{2E\sqrt{E}}$$

$$\frac{\partial \bar{a}}{\partial u} = \frac{L}{\sqrt{E}} \bar{n} - \frac{E_2}{2G\sqrt{E}} \bar{r}_2$$

$$\bar{b} = \frac{\bar{r}_2}{\sqrt{G}}$$

$$\bar{r}_2 = \bar{b}\sqrt{G}$$

$$\frac{\partial \bar{a}}{\partial u} = \frac{L}{\sqrt{E}} \bar{n} - \frac{E_2}{2G\sqrt{E}} \bar{b}\sqrt{G}$$

$$= \frac{L}{\sqrt{E}} \bar{n} - \frac{E_2}{2\sqrt{EG}} \bar{b}$$

jadi vektor kelengkungan :

$$\bar{K} = \frac{L}{E} \bar{n} - \frac{E_2}{2E\sqrt{G}} \bar{b}$$

$$\bar{K}_n = \frac{L}{E}$$

$$\bar{K}_g = \frac{-E_2}{2E\sqrt{G}}$$

Kelengkungan geodetik dari kurva parameter  $v = \text{konstan}$  adalah negatif dari divergen unit vektor  $\bar{b}$ .

Dari ( 2.4.3 ) diketahui :

$$\text{div } \bar{\alpha} = \frac{1}{H} \left\{ \frac{\partial}{\partial u} (HP) + \frac{\partial}{\partial v} (HQ) \right\} - \int R$$

$$\bar{b} = \frac{\bar{F}_2}{\sqrt{G}}$$

$$\begin{aligned} \text{div } \bar{b} &= \text{div} \left( \frac{\bar{F}_2}{\sqrt{G}} \right) \\ &= \frac{1}{H} \frac{\partial}{\partial v} \left( \frac{H}{\sqrt{G}} \right) \end{aligned}$$

karena  $F = 0$ , maka :

$$\begin{aligned} \text{div} \left( \frac{\bar{F}_2}{\sqrt{G}} \right) &= \frac{1}{\sqrt{EG}} \frac{\partial}{\partial v} \frac{\sqrt{EG}}{\sqrt{G}} = \frac{1}{\sqrt{EG}} \frac{\partial}{\partial v} \sqrt{E} \\ &= \frac{1}{\sqrt{EG}} E_2 \cdot \frac{1}{2} E^{-\frac{1}{2}} \\ &= \frac{E_2}{2E\sqrt{G}} \end{aligned}$$

$$\text{div} \left( \frac{\bar{F}_2}{\sqrt{G}} \right) = -\bar{K}_g$$

Hasil yang sama dapat diperoleh dengan menganggap  $u = \text{konstan}$

Vektor kelengkungan :

$$\bar{K} = \frac{1}{\sqrt{G}} \frac{\partial \bar{b}}{\partial v}$$

$$\frac{\partial \bar{b}}{\partial v} = \frac{\partial}{\partial v} \left( \frac{\bar{F}_2}{\sqrt{G}} \right) = \frac{1}{\sqrt{G}} \bar{F}_{22} - \frac{G_2 \bar{F}_2}{2G\sqrt{G}}$$

$\bar{F}_{22}$  dihitung terlebih dulu :

$$\bar{F}_{22} = N\bar{n} + p\bar{r}_1 + q\bar{r}_2$$

$$\bar{F}_1 \cdot \bar{F}_{22} = F_2 - \frac{1}{2}G_1$$

$$\bar{F}_2 \cdot \bar{F}_{22} = \frac{1}{2}G_2$$

$$\bar{F}_1 \cdot \bar{F}_{22} = (N\bar{n} + p\bar{r}_1 + q\bar{r}_2) \cdot \bar{F}_1$$

$$\bar{F}_1 \cdot \bar{F}_{22} = pE + qF$$

$$= F_2 - \frac{1}{2}G_1$$

$$\bar{F}_2 \cdot \bar{F}_{22} = pF + qG = \frac{1}{2}G_2$$

$$1 \times F \implies pEF + qF^2 = FF_2 - \frac{1}{2}FG_1$$

$$2 \times E \implies pEF + qEG = \frac{1}{2}EG_2 \quad -$$

$$q(F^2 - EG) = FF_2 - \frac{1}{2}FG_1 - \frac{1}{2}EG_2$$

$$q(EG - F^2) = \frac{1}{2}FG_1 + \frac{1}{2}EG_2 - FF_2$$

$$q = \frac{1}{2H^2} (FG_1 + EG_2 - 2FF_2)$$

$$1 \times G \implies pEG + qFG = F_2G - \frac{1}{2}GG_1$$

$$2 \times F \implies pF^2 + qFG = \frac{1}{2}FG_2 \quad -$$

$$p(EG - F^2) = F_2G - \frac{1}{2}GG_1 - \frac{1}{2}FG_2$$

$$p = \frac{1}{2H^2} (2F_2G - GG_1 - FG_2)$$

kurva parameter orthogonal :

$$F = 0$$

$$H^2 = EG$$

$$\bar{F}_{22} = N\bar{n} + \frac{1}{2EG} (-GG_1) \bar{r}_1 + \frac{1}{2EG} (EG_2) \bar{r}_2$$

$$\bar{r}_{2,2} = N\bar{n} - \frac{G_1}{2E} \bar{r}_1 + \frac{G_2}{2G} \bar{r}_2$$

$$\begin{aligned} \frac{\partial \bar{b}}{\partial v} &= \frac{1}{\sqrt{G}} \left( N\bar{n} - \frac{G_1}{2E} \bar{r}_1 + \frac{G_2}{2G} \bar{r}_2 \right) - \frac{G_2 \cdot \bar{r}_2}{2G\sqrt{G}} \\ &= \frac{N\bar{n}}{\sqrt{G}} - \frac{G_1}{2E\sqrt{G}} \bar{r}_1 + \frac{G_2}{2G\sqrt{G}} \bar{r}_2 - \frac{G_2 \cdot \bar{r}_2}{2G\sqrt{G}} \end{aligned}$$

$$\frac{\partial \bar{b}}{\partial v} = \frac{N\bar{n}}{\sqrt{G}} - \frac{G_1}{2E\sqrt{G}} \bar{r}_1$$

diketahui :

$$\bar{a} = \frac{\bar{r}_1}{\sqrt{E}} \implies \bar{r}_1 = \bar{a} \sqrt{E}$$

$$\bar{K} = \frac{1}{\sqrt{G}} \left( \frac{N\bar{n}}{\sqrt{G}} - \frac{G_1}{2E\sqrt{G}} \cdot \bar{a} \sqrt{E} \right)$$

$$\bar{K} = \frac{N}{G} \bar{n} - \frac{G_1}{2G\sqrt{E}} \bar{a}$$

kelengkungan geodetik dari  $u = \text{konstan}$ :

$$\bar{K}_g = \frac{G_1}{2G\sqrt{E}}$$

$$\bar{K}_g = \text{div } \bar{a}$$

$$= - \text{div} ( -\bar{a} )$$

$$\text{div } \bar{a} = \text{div} \left( \frac{\bar{r}_1}{\sqrt{E}} \right)$$

$$= \frac{1}{H} \frac{\partial}{\partial u} \left( \frac{H}{\sqrt{E}} \right)$$

$$F = 0$$

$$\text{div } \bar{a} = \frac{1}{\sqrt{EG}} \frac{\partial}{\partial u} \left( \frac{\sqrt{EG}}{\sqrt{E}} \right)$$

$$= \frac{1}{\sqrt{EG}} \frac{\partial}{\partial u} \sqrt{G}$$

$$= \frac{1}{\sqrt{EG}} G_1 \cdot \frac{1}{2} G^{-\frac{1}{2}}$$

$$\operatorname{div} \bar{a} = \frac{G_1}{2G\sqrt{E}}$$

Jadi kelengkungan geodetik dari kurva parameter  $u = \text{konstan}$  adalah sama dengan  $\operatorname{div} \bar{a}$ .

Pandang  $\phi(u, v) = \text{konstan}$ .

Kelengkungan geodetik dari  $\phi(u, v)$  didapat dengan menggunakan rumus Bonnet's.

Vektor satuan tegak lurus pada kurva adalah :  $\frac{\nabla \phi}{|\nabla \phi|}$

$$|\nabla \phi| = \frac{1}{H} \sqrt{E\phi_2^2 - 2F\phi_1\phi_2 + G\phi_1^2}$$

$$\nabla^2 \phi = \frac{1}{H} \frac{\partial}{\partial u} \left( \frac{G\phi_1 - F\phi_2}{H} \right) + \frac{1}{H} \frac{\partial}{\partial v} \left( \frac{E\phi_2 - F\phi_1}{H} \right)$$

$$\bar{K}_g = \operatorname{div} \frac{\nabla \phi}{|\nabla \phi|} = \nabla \cdot \frac{\nabla \phi}{|\nabla \phi|}$$

$$\bar{K}_g = \frac{\frac{1}{H} \frac{\partial}{\partial u} \left( \frac{G\phi_1 - F\phi_2}{H} \right) + \frac{1}{H} \frac{\partial}{\partial v} \left( \frac{E\phi_2 - F\phi_1}{H} \right)}{\frac{1}{H} \sqrt{E\phi_2^2 - 2F\phi_1\phi_2 + G\phi_1^2}}$$

$$\bar{K}_g = \frac{1}{H} \sqrt{E\phi_2^2 - 2F\phi_1\phi_2 + G\phi_1^2}$$

$$\bar{K}_g = \frac{1}{H} \left\{ \frac{\partial}{\partial u} \left( \frac{G\phi_1 - F\phi_2}{\sqrt{E\phi_2^2 - 2F\phi_1\phi_2 + G\phi_1^2}} \right) + \frac{\partial}{\partial v} \left( \frac{E\phi_2 - F\phi_1}{\sqrt{E\phi_2^2 - 2F\phi_1\phi_2 + G\phi_1^2}} \right) \right\}$$

Bila  $\bar{t}$  adalah garis singgung satuan, vektor satuan tegak lurus pada kurva adalah  $\bar{n} \times \bar{t}$ :

$$\bar{K}_g = -\operatorname{div} (\bar{n} \times \bar{t})$$

$$= -\nabla \cdot (\bar{n} \times \bar{t})$$

$$= \bar{n} \cdot \nabla \times \bar{t} - \bar{t} \cdot \nabla \times \bar{n}$$

$$\operatorname{kurl} \bar{n} = \nabla \times \bar{n} = 0$$

maka :

$$\begin{aligned}\bar{K}g &= \bar{n} \cdot \nabla \times \bar{t} \\ &= \bar{n} \cdot \text{kurl } \bar{t}\end{aligned}$$

Maka didapatkan suatu teorema :

Bahwa jika diberikan famili kurva pada permukaan dengan tanda positif sepanjang kurva, kelengkungan geodetik dari anggota famili adalah hasil kali skalar dari normal dengan kurl garis singgung.

